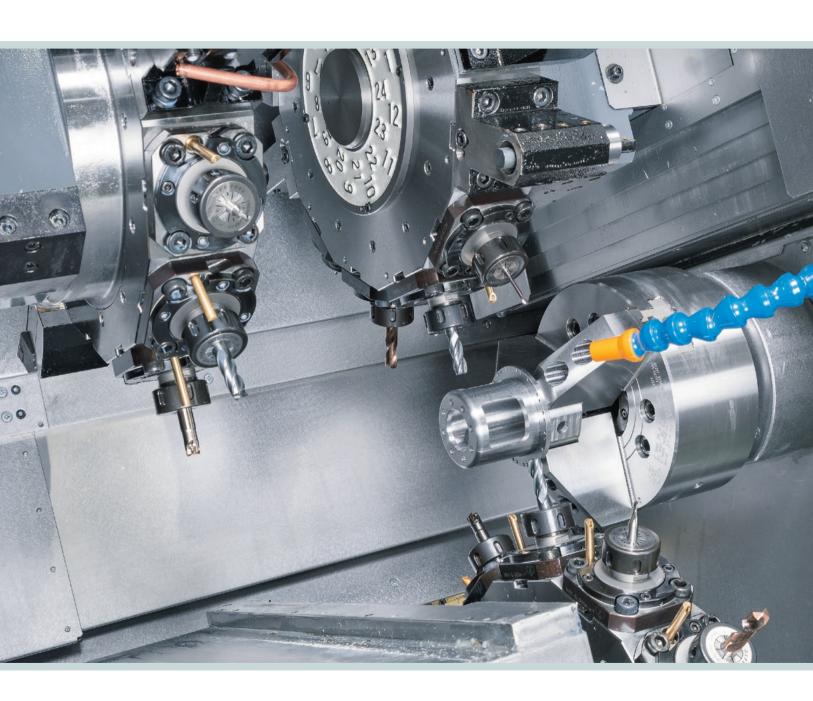
# GENERAL CATALOG

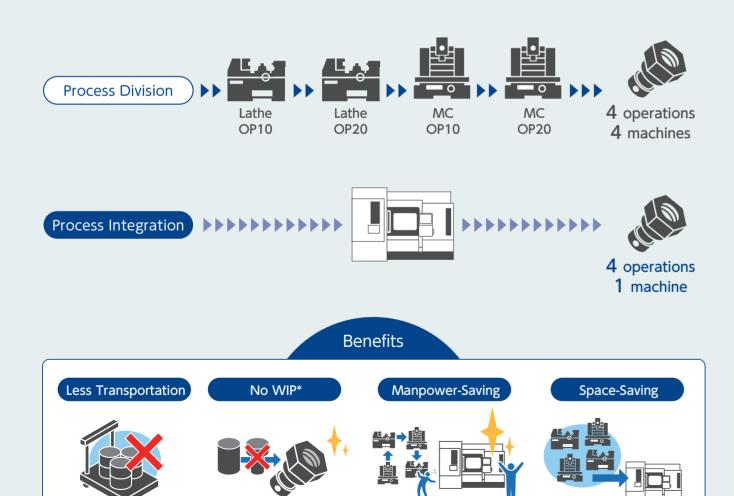


NAKAMURA-TOME PRECISION INDUSTRY CO.,LTD.

# From Blank Materials to Finished Products in ONE MACHINE

Nakamura-Tome's multitasking machines can handle various processing methods such as turning, milling, hobbing, and more. In other words, even for workpieces with multiple processing steps, it is possible to process everything to the finished products with just one machine by simply loading blank materials. These are some of the many benefits of making a part complete with a single multitasking machine:

- Reduction of Transportation costs.
- Reduction of Work-in-progress inventory.
- Reduction of Operator man-hours.
- Reduction of Floor space, etc.



\* WIP: Work-in-progress

# Wide Range of Capabilities

# **Product Line-up**



We meet our customers' needs with a wide range of machine configurations in our lineup and strong adaptability to work requirements.







			I			1			
				JX-200			JX-	-250	
		Unit	φ51	φ65	φ80(op.)	φ65	φ71(op.)	φ80(op.)	φ90(op.)*1
Capacity									
Max. turning diameter / Max.		mm		325 / 1,058			320 / 1,650		320 / 1,587
Distance between spindles	[max. / min.]	mm		1,250 / 240			1,850 / 300		1,787 / 237
Distance between centers [	max. / min.]	mm		_				-	
Bar capacity	L	mm	-	φ65	φ80(op.)	φ65	φ71(op.)	φ80(op.)	φ90(op.)
	R	mm	φ51	φ65(op.)	-		Ψ7 1(ορ.)	_	_
Chuck size		inch		6",8"		8", 10", 12", 15"		8", 10", 12"	
Slide travel									
Y-axis slide travel		mm		Y1:±105/Y2:±35		Y1:±12	25 / Y2:±40 /(op. \		Y1: ±125 / Y2: ±40 / -
B2-axis slide travel		mm		770			1,5	550	
L/R spindle									-
Spindle speed	L		-	4,500	3,500	4,500	4,500	3,500	2,500
	R		6,000	4,500(op.)	-	4,500 *2	4,500	-	-
Spindle motor	L	kW	-	15/11	18.5/15		5/15	18.5/15, 22/18.5	
	R		11/7.5	15/11 (op.)		18.5/15	18.5/15, 15/11	-	-
Tailstock(op.)									
Driving system		-							
Quill taper		-		-					
Range of thrust force		kN		-				_	
■ Tool spindle		min-1		12.000 ( 10.000)			12.000 (-	- 10.000\	
Tool spindle speed		kW		12,000 (op. 18,000)				p. 18,000)	
Tool spindle motor  B-axis swiveling range		_ KVV		15/11 ±95°				20°	
Tool coupling type				CAPTO C6 (op. HSK-T63)				(op. HSK-T63)	
■ ATC				CAF10 C0 (op.113K-103)			CAPTO CO	(υμ. 113κ-103)	
Number of tools		_		80 (op. 40, 120)			90 (00	40, 120)	
Long-tool ATC storage capacity	v / Length(on )	_ /mm		- 00 (op. 40, 120)			* 1	-	
Lower turret	y / Length(op.)	7111111							
Number of turrets		_		1			1 (c	p. 2)	
Type of turret head / Number o	f indexing nos	_	Г	odecagonal drum turret /	24			drum turret / 24	
Milling spindle speed	acx8 pos.	min-1		6,000 (op. 8,000)				000	
Milling motor		kW		5.5/3.7				/3.7	
General				3.37 3.7			3.3	, 3.,	
	Height			2.925			2.0	954	
Machine Dimensions	Width	mm		5.250				78.5	
	Depth			2,987.2				57.7	
Machine weight (incl. contro		kg		23,000				.000	
0				,,,,,					

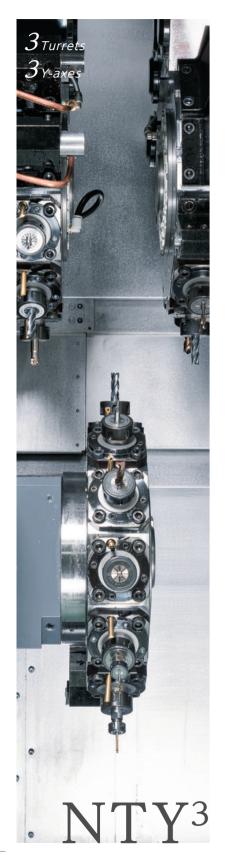
\*2 There is limitation on maximum spindle speed with 15-inch chuck.







M	X-100				NTRX-300	0			N	TRX-300	)L	
φ51	φ65	(op. )	φ65	φ71(op.)	φ80A(op.)	φ80B(op.)	φ90(op.)	φ65	φ71(op.)	φ80A(op.)	φ80B(op.)	φ90(op.)
305	5 / 834				640 / 1,100					640 / 1,600		
	0 / 230				1,350 / 250					1,850 / 300		
	_				1,225 / 125			1,725 / 175 *6				
φ51	φ65	(op.)	- φ65 φ71(op.) φ80(op.) *3 φ80(op.) *4 φ90(op.) *4			- 465   471(op)   480(op) *3   480(op) *4				φ90(op.) φ80(op.) *4		
	8"		8", 10"							8", 10"		
V/4 - 1 4/	25 ( ) ( ) -				1405					1405		
	05 / Y2: - 770				±125				1 550	±125 (1,015 / Stead	ly roct)	
	770				1,100				1,550	(1,015 / 3teac	iy rest)	
6,000	3,4,	500	4,500	3,500	3,500	2,500	2,500	4,500	3,500	3,500	2,500	2,500
11/7.5	15.	/11	15/11 / 22	15/11 / 22/18.5(op.) 22/18.5(o				15/11 / 22	2/18.5(op.)		22/18.5(op.)	)
11/7.5	-	_	15/11 / 22/18.5(op.) 22/18.5(op.) –					15/11 / 22	2/18.5(op.)	22/18	.5(op.)	-
	<del>-</del>		NC control servo-driven type  MT-5(Built-in center)							trol servo-dri -5(Built-in cer		
			2.5 ~ 6.5						////	2.5 ~ 6.5	iter)	
					2.5 0.5					2.5 0.5		
12,000 (	op. 20,000)				3,000 (op. 12,00	00)			8,	000 (op. 12,0	00)	
1	1/7.5				22/15			22/15				
	±95°				-120°, +105°			±120°				
CAPTO C4	(op. HSK-T40)			CAF	PTO C6 (op. HSk	(-A63)		CAPTO C6 (op. HSK-A63)				
26 (0)	o. 48, 72)				0 (op. 60, 80, 1	20)			40	(op. 60, 80, 1	120)	
30 (0)	J. 40, 72) —			4	— (op. 60, 60, 1	20)				/ φ65× L450		
										. ,		
	1				-					-		
Dodecagonal	drum turret / 24				-					_		
	6,000 6,000 8,000(op.)		-							_		
7.1/2.2	7.1/2.2	6/1.5 (op.)	-									
	,662				2,615					2,615		
	,350				4,529			5,440				
	,795		2,670					2,670				
14	4,000				17,000			19,000				





				NTY <sup>3</sup> -100V	
	(	Jnit	φ42	φ51(op.)	φ65(op.)
Capacity					
Max. turning diameter	12st	mm _		200	
viax. turning diameter	15st '			190	
Max. turning length		mm		588	
Distance between spindles [r min.]	max. /	mm		820 / 200	
Par canacity	L .		φ42	4E1(on)	φ65(op.)
Bar capacity -	R	mm	Ψ42	φ51(op.)	-
Chuck size	L/R i	nch		6" / 6"	
Slide travel					
/1/Y2/Y3 axis slide travel	12st	mm _		±42 / ±42 / ±32.5	
	15st			±31	
32-axis slide travel	ı	mm		620	
L/R spindle					
Spindle speed	L n	nin <sup>-1</sup>	6.000	6.000	5,000
· · · · · · · · · · · · · · · · · · ·	R				-
Spindle motor	<u> </u>	kW	11/7.5	11/7.5 (op. 15/11)	11/7.5 (op. 15/11)
I I I a a a a // a	R				_
Upper/Lower turret  Number of turrets(Upper/Lov	wor)			2/1	
Type of turret head / Number of indexing pos.	12st 15st	-		Dodecagonal drum turret / 24 15 stations turret / 15	
Milling	1331			15 stations turiet / 15	
	12st			6,000 (op. 10,000)	
Milling spindle speed	15st n	nin <sup>-1</sup>		6,000	
Milling motor		kW		7.1/2.2 (op. 7.5/2.2)	
	12st			Individual rotation / 12	
Rotary system / Number of milling stations	15st			Individual rotation / 15	
General					
	Height			2,255.3	
Machine Dimensions	Width r	mm		3,864.2	
	Depth			2,245.7	
Machine weight (incl. control	)	kg		10,000	





NTY	3-150		NTY	<sup>73</sup> -250				
φ51	φ65(op.)	φ51	φ65	φ71(op.)	φ80(op.)			
22	25		225		180			
-				-				
68				/ Lower : 905.5				
970 /	200		1,200	0 / 255				
φ51	φ65(op.)	-	φ65	φ71(op.)	φ80(op.)			
	-	φ51	φ65 (op.)					
6" /	6"		8"	/ 6"				
±45 / ±4	45 / ±35		-61. +51 / -61.	, +51 / -51, +61				
		-						
77	70		9	145				
	<u> </u>							
5,000	4,500	-	E 000 (a	op. 4,000)	3,500			
5,000	-	5,000	5,000 (0	pp. 4,000)	-			
15/	′11	- 18.5/11 (op. 26/22)						
11/7.5 (o	p.15/11)	18.5 / 11 –						
2 /				/ 1				
Dodecagonal d	rum turret / 24		Dodecagonal	drum turret / 24				
_	-			-				
6,000 (op			6,1	000				
-								
5.5/				5/3.7				
Individual ro				rotation / 12 –				
2,2	00			395				
3,8				900				
2,2				580				
10,5				,425				





				WY-100V				
		Unit	φ42	φ51(op.)	φ65(op.)			
Capacity								
Max. turning diameter	12st	mm		200				
Max. turriirig urairieter	15st	""""		190				
Max. turning length		mm		588				
Distance between spindles [ma	ax. / min.]	mm		820 / 200				
Bar capacity	L	mm	φ42	φ51(op.)	φ65(op.)			
sai capacity	R	"""	Ψ42	ψ51(ορ.)	-			
Chuck size	L/R	inch		6" / 6"				
Slide travel								
Y1/Y2 axis slide travel	12st	mm		±42 / ±32.5				
11/12 axis stide travet	15st	"""		±31				
32-axis slide travel		mm		620				
L/R spindle								
Spindle speed	L	min-1	6.000	6.000	5,000			
omate speed	R		0,000	0,000	-			
Spindle motor	L	kW	11/7.5	11/7.5 (op. 15/11)	11/7.5 (op. 15/11)			
pinate motor	R	KVV	1177.5	-				
Upper/Lower turret								
Number of turrets(Upper/Lo	wer)	-		1/1				
ype of turret head /	12st			Dodecagonal drum turret / 24				
Number of indexing pos.	15st			15 stations turret / 15				
Milling								
Milling spindle speed	12st	min-1		6,000 (op. 10,000)				
viittiilg spiilate speed	15st			6,000				
Ailling motor		kW		7.1/2.2 (op. 7.5/2.2)				
Rotary system / Number of	12st			Individual rotation / 12				
milling stations	15st		Individual rotation / 15					
General								
Machine Dimensions	Height			2,255.3				
	Width	mm		3,849.1				
	Depth			2,245.7				
Machine weight (incl. contro	5I)	kα		9.500				





	WY-150V			WY-	250L			
φ51	φ65(op.)	φ80(op.)	φ51	φ65(R op.)	φ71(op.)	φ80(op.		
	225			225		180		
	-				-			
	685			9	10			
	970 / 200			1,200	/ 255			
φ51	φ65(op.)	φ80(op.)	-	φ65	φ71 (op.)	φ80 (op		
		-	φ51	φ65 (op.)	-	_		
	6", 8"	8"		8"	/ 6"			
	±45 / ±35				-50,+20			
	-		945					
	770			9	45			
		4,000	_	4,500	4,000	3,500		
6,000	5,000	_	5,000	4,500	-	-		
		28/15	_		18.5/11 (op. 26/22)			
15/11	18.5/11	-	15/11 (op. 18.5/15)					
	1/1			1				
	Dodecagonal drum turret / 24		Dodecagonal drum turret / 24					
	-				_			
	10,000			6.0	000			
	-				_			
	7.5/3.7							
	Individual rotation / 12		5.5/3.7 (op. 7.5/3.7) Individual rotation / 12					
	-				-			
	2,280			2,3	395			
	4,245.2			4,6	520			
	2,389.7			2,!	593			
	11,000			13,	000			





NT-Flex



		NT-l	Flex	WT-100
	Unit	φ32	φ38(op.)	φ42
Capacity				
Max. turning diameter Lower	mm	15	0	190
Max. turning length	mm	25	60	503
Distance between spindles (max. / min.)	mm	655 /	200	735 / 210
Bar capacity L	mm	φ32	φ38 (op.)	φ42
Chuck size	inch	5		6"
Slide travel				
Y-axis slide travel (Upper)		±2	25	±31
B2-axis slide travel		45	5	525
L/R spindle				
Spindle speed R	min <sup>-1</sup>	8.000		6,000
Spindle motor R		7.5/	5.5	11/7.5
Upper/Lower turret				
Number of turrets(Upper/Lower)		1 /	1	1 / 1
Type of turret head / Number of indexing pos.	-	Dodecagonal d	rum turret / 24	Dodecagonal drum turret / 24
Milling				
Milling spindle speed	min <sup>-1</sup>	8,000 (op	. 10,000)	6,000
Milling motor	kW	7.1/2.8 (op	o. 7.5/2.2)	7.1/2.2
Rotary system / Number of milling stations		Individual ro	otation / 12	Individual rotation / 12
General				
Height		2,2	13	1,940
Machine Dimensions Width	mm	3,5	00	2,630
Depth		1,3	80	1,923
Machine weight (incl. control)	kg	6,5	00	5,700









WT-150II

WT-250II

WT-300

φ <b>51</b>	φ65(op.)		250II		VV I	WT-300			
10	φοσ(ορ.)	φ51	φ65	φ65	φ71(op.)	φ80(op.)	φ102(op.)		
10									
	20	25	.0		270	199	199		
15	90	25	SU .		270	270	270 (L: φ102 / R: φ6 229 (L: φ102 / R: φ10		
51	5	55	55		7	80			
800 /	′ 200	885 / 265 (L: 870 / 250 (L:			1,100 / 250				
φ51 φ65 (op.)		-	φ65	φ65	φ71 (op.)	φ80 (op.)	φ102 (op.)		
φ51 – 6", 8" *8		φ51	φ65 (op.)	φοσ	_	-	φ102 (op.)		
6", 8	**8	8",	6"		8"		12"		
±35 (op.)		±41	(op.)	±6	0 (op.)	±4	0 (op.)		
60	00	62	20		8	50			
5,000	4,500	-	4,500	4.500	4,000	3,500	2,500		
5,000	-	5,000	4,500(op.)	4,500	_	_	2,500		
15/	/11	18.5/15 (op. 35/26/22, 15/11 Wide range)		15/11 (op. 18.5/15, 22/18.5)					
11/	7.5	11/7.5 (op. 15	5/11, 18.5/15)	15/11 (op. 18.5/15)					
1 /	′ 1	1 /	1		1	/ 1			
Dodecagonal d	rum turret / 24	Dodecagonal d	rum turret / 24	Dodecagonal drum turret / 24					
6,000	)(op.)	6,000 (L:65 3,600 (L:65	/ R:51)(op.)		3,60	0(op.)			
5.5/3.	7(op.)	5.5/3.		5.5/3.7(op.)					
Individual rotation / 12(op.)		Individual rota	ation / 12(op.)		Individual rot	ation / 12(op.)			
1,858.5		2,2	25		2,	276			
3,6	75	4,0	59	4,230	4,:	275	4,345		
2,25	58.2	2,3	14	2,487					

# NTJ series / TW series

\* The photos of the machines shown in the chart include some options.



			NTJ	-100	Supe	r NTJ	
		Unit	φ51	φ65(op.)	φ65	φ51	
Capacity							
Max. turning diameter		mm	17	5	19	90	
Max. turning length		mm	67	'8	6	20	
Distance between spindle	es [max. / min.]	mm	910 /	200	970	/ 210	
Bar capacity	L R	mm	φ51	φ65(op.)	φ65 -	φ51(op.) φ51	
Chuck size		inch	6	•	(	5"	
Slide travel							
Y1/Y2 axis slide travel		mm	±40 /	±32.5	±45	5/-	
B2-axis slide travel		mm	68	0	7	60	
L/R spindle							
Spindle speed	L R	min-1	5,000	4,500	4,500 —	5,000	
Caladia assess	L	LAA	11/	7.5	15	/11	
pindle motor R		kW	11/	7.5	11/	/7.5	
Upper/Lower turret							
Number of turrets(Upper	/Lower)	-	1 /	1	1.	/ 1	
Type of turret head / Nur indexing pos.	mber of	-	Dodecagonal d	rum turret / 24	Dodecagonal o	drum turret / 24	
Sta Number of tool	ndard		Turning/M 24/0 -		Turning/Milling tool 24/0 - 0/12		
	ra tools ecifications(op.)		Turning/M 24/0 -		-		
Swiveling range(Upper)		-	±9	1°	±9	91°	
Milling spindle speed		min <sup>-1</sup>	6,0	00	6,0	000	
Milling motor	ing motor k		7.1/	2.2	5.5	/3.7	
General				•	•		
	Height		2,5	65	2,	170	
Machine Dimensions	Width	mm	3,7	99	3,6	3,660	
S.IIICHSIOIIS	Depth		2,1	10	2,320		
Machine weight (incl. cor	ntrol)	kg	10,0	000	12,	500	





			NEW TW-30
		Unit	φ71
■ Capacity			
Max. turning diameter			335 (op. large swing spec. 400)
Max. turning length		mm	300
Distance between spindles [max. / min.]		mm	1,300 / 320
Bar capacity		mm	φ71
Chuck size		mm	10"
Slide travel			
RZ-axis slide travel		mm	980
L/R spindle			
Spindle speed			3,500
Spindle motor	L	kW	22/18.5
Spiriate motor	R	KVV	22/18.5
Upper turret			
Number of turrets		-	2
Type of turret head / Numbindexing pos.	per of	-	Dodecagonal drum turret / 12
Milling (op.)			
Milling spindle speed		min-1	6,000
Milling motor			7.5/3.7
General			
	Height		2,250
Machine Dimensions Width		mm	4,370
	Depth		2,125
Machine weight (incl. contr		kg	14,500



1 Turret





			SC-100X <sup>2</sup>	SC-100	SC-	-200II	SC-20	0IIL *11	
		Unit	φ51	φ51	φ65	φ71(op.)	φ65	φ71(op	
■ Capacity						•			
Max. turning diameter		mm	195	230	390 / 340	)(op. 16st) *9	390 / 34	0(op. 16st)	
Max. turning length			400	400 / 300(op. Tailstock)	3	17.8	52	22.8	
Distance between centers	;	mm	-	430	!	510	715		
Bar capacity		mm	φ51	φ51	φ65 φ71		φ65 φ		
Chuck size		mm	6"	6"	8*	10"	8"	10"	
Slide travel	,								
Y-axis slide travel		mm	±40	±40	±50 *10		±	:50	
Spindle		,							
Spindle speed			6,000	5,000	4	,500	4,500		
Spindle motor		kW	11/7.5	11/7.5	15/11(op. 18.5/15)		15/11 (op. 18.5/1		
Turret									
Type of turret head /	ype of turret head /		Upper: Dodecagonal / 24 Lower: Flexible special design turret / 9	Dodecagonal / 24	Dodecagonal / 24		Dodecagonal	drum turret /	
Number of indexing pos.		15st	-	-		-		-	
		16st	-	-	Hexadeca	agon / 16 *9	Hexadeo	agon / 16	
Milling									
Milling spindle speed		min <sup>-1</sup> 12st	6,000	6,000		,000		000	
			7.1/2.2	7.1/2.2	5.5/3.7		5.5	5/3.7	
Milling motor(kW)		15st	-	-		-		-	
		16st	-	-	5.5/3.7		5.5/3.7		
		12st	12	12		12		12	
Number of milling stations		15st	-	-	-		-		
		16st	-	-	1	6 *9	16		
Tailstock (op.)							1		
Driving System		-	•	NC control servo-driven type	NC control se	ervo-driven type	NC control se	rvo-driven ty	
Travel		mm	-	400		305		70	
Quill taper			-	MT-3 (Rotating center)	MT-4 (Rot MT-3 (Bu	ating center), ilt-in center)	MT-4 (Rota MT-3 (Bui	ating center), lt-in center)	
Sub spindle (op.)			standard					12	
Chuck size / Bar capacity		mm	5"(6") / φ42	5*(6") / φ42		-	6", 8"	/ φ51	
kW		min <sup>-1</sup> / kW	6,000 / 7.5/5.5	6,000 / 7.5/5.5		-	5,000	/ 15/11	
Distance between spindles [r	tance between spindles [max. / min.] mm		600 / 200	600 / 200	-		800 / 260		
B-axis slide travel			-	400		-	5	40	
General									
	Height		1,799	1,780	2	,125	2,	125	
Machine Dimensions	Depth	mm	3,072	2,524	3	,195	3,7	'87.5	
	Width		1,974	1,825	1	,967	1,	967	







SC-450L

AS	3-200	AS	-200L	SC-	-300II	SC-	-300IIL	SC-	-450L	
φ65	φ71(op.)	φ65	φ71(op.)	φ71	φ89(op.)	φ71	φ89(op.)	φ81	φ89(	
290 / 28	30(op. 15st)	290 / 28	30(op. 15st)		360		360		180	
	300	570		600 (Tailstock	), 635 (R Spindle)	1,100 (Tailstocl	k), 1,135 (R Spindle)	1,	.520	
Á	427		760	7	13.5	1	213.5	1,752		
φ65	φ71	φ65	φ71	φ71	φ89	φ71	φ89	φ81 φ8		
	8*		8"	10	", 12"	10", 12"		12" 1		
:	±41		±41	=	±60		±60	±7	5(op.)	
	3,000(op.) / orque-up motor)		3,000(op.) / rque-up motor)	3.	500	3	3,500	2.	500	
	5/11		5/11	22	/18.5	22	2/18.5	30	0/22	
Dodeca	Dodecagonal / 24 Dodecagonal / 24		agonal / 24	Dodeca	gonal / 24	Dodecagonal / 24		Dodecagonal drum turre		
15 stations turret / 15 15 st		15 station	ns turret / 15		-		-		_	
-		-	Hexade	cagon / 16	Hexade	ecagon / 16		-		
6,	6,000 6,000		,000	6	.000	6	5,000	3,60	00(op.)	
5.	5/3.7	5.	5/3.7	7.5	5/3.7	7.	.5/3.7	5.5/2	3.7(op.)	
5.	5/3.7	5.	5/3.7		-		-		-	
	-		-	5.5/3.7		5.5/3.7		-		
	12		12		12	12		12(op.)		
	15		15		-		-			
	-		-		16		16		-	
Ma	anual	M	anual	NC control se	ervo-driven type	Z-axis slide NC control s	e (knock type) / servo-driven type	NC control se	ervo-driven ty	
1	200		435		500		/ 1,000	1,	.490	
MT-4(Rota	ating center)	MT-4(Rot	ating center)	MT-5 (Rotating center), MT-4 (Built-in center)		MT-5 (Rotating center), MT-4 (Built-in center)		MT-5 (Rotating ce	enter, Built-in	
	-	6"	/ φ42	6" 9	" / <b>ø</b> 51	6" 5	Β" / φ51	10"	/ φ71	
	-		/ 7.5/5.5		/ 15/11		0 / 15/11		/ 15/11	
	-		0 / 220 580		600	1,310 / 310			/ 485.5 208.5	
							.,000	1,2	-00.5	
1,	.852	1	,935	2	300	2,300		2,184.9 / 2,531.3 (op. Y-ax		
1.	,655	2	,716	3	995	4,902		5,050		
1,	,665		,805	2	,130		2,130		2,164.8	
1	500		500	0	000		1 000	9.000 / 10.000 (op. Y-axis)		

\*11 NC tailstock (MT-4/Rotating center) specification is standard. \*12 When the sub spindle specification is selected, the dodecagonal turret is not selectable.

<sup>\*9 16</sup>st cannot be selected for specifications without milling.

<sup>\*10</sup> Y-axis cannot be selected for specifications without milling.
With or without Y-axis can be selected for specifications with milling.

# Gantry Loader 1











			GR-210 High-Speed		GR-210 NEW		
<b>*1</b>		Unit	10kg	20kg (op.)	10kg	20kg (op.)	
Speed							
Loading/Unloading t	ime *2	sec	6.0/6.0	10.5/10.5	10.5/	/10.5	
Hand							
Workpiece	Flange		Ф20~	Ф220	Φ20~	Ф220	
diameter	Shaft	mm	Φ20~	Ф100	Φ20~	Ф100	
Workpiece length	Flange		20~	100	20~	100	
workpiece teligtii	Shaft	- mm	50~	200	50~	200	
Hand turning	Flange		0.75sec/180°	3.0sec/180°	1.8sec/180°	3.0sec/180°	
Hallu tullillig	Shaft		1.8sec	z/180°	1.8sec	:/180°	
Hand back turning							
Workpiece weight	Flange	kg	10×2	20×1	10×2	20×1	
Workpiece weight	Shaft	Kg	102	20/1	10^2	20/1	
Jaw stroke	Flange	- mm	Ф40	Ф32	Ф40	Ф32	
Jaw Stioke	Shaft		Ф30		Ф30		
Work Stocker List							
		WS-221	-	-	-	-	
Multi-layer work sto	ckor	WS-231	-	-	-	-	
Mutti-tayer work stor	CKEI	WS-442W	0	0	0	0	
		WS-445W	0	0	0	0	
		WS-121	-	-	-	-	
Single layer weak ste	ockor	WS-122	-	-	-	-	
Single-layer work sto	Single-layer work stocker		-	-	-	-	
		WS-132	-	-	-	-	
HAKO-BEI Rail extension is requ selected.	uired when B	type is	-	-	-	-	

			GR-203 H	ligh-Speed	GR-203II		
<b>*</b> 1		Unit	3kg	5kg (op.)	3kg	5kg (op.)	
Speed							
Loading/Unloading	time *2	sec	4.7/4.6	6.7/6.7	7.8/7.8	8.1/8.1	
Hand							
Workpiece	Flange		Ф20~	- Ф130	Φ20~	Ф130	
diameter	Shaft	- mm	Φ15 <sup>-</sup>	~ Ф30	Φ15~	Ф30	
Workpiece length	Flange	mm	20-	-110	20~	110	
workpiece teligili	Shaft		35^	~200	35~	200	
Hand turning	Flange		0.9~1.1sec/90°		1.4~1.69	sec/90°	
nand turning	Shaft		1.2se	c/180°	1.2sec/180°		
Hand back turning				-	-		
Workpiece weight	Flange	kg	3.0×2	5.0×2	3.0×2	5.0×2	
workpiece weight	Shaft		1.0×2		1.0×2		
Jaw stroke	Flange	- mm	Ф16		Ф16		
Jaw Stioke	Shaft	"""	Ф25		Ф25		
Work Stocker List							
		WS-221	0	0	0	0	
Multi-layer work sto	ockor	WS-231	0	0	0	0	
Mutti-tayer Work Sto	ckei	WS-442W	-	-	-		
		WS-445W	-	-	-	-	
		WS-121	0	0	0	0	
Single-layer work st	ocker	WS-122	0	0	0	0	
Jingle-layer Work St	Single-layer work stocker		0	0	0	0	
		WS-132	0	0	0	0	
HAKO-BEI Rail extension is req selected.	uired when B	type is	0	0	0	0	

<sup>\* 1</sup> Specifications may differ for each model to be installed.
\* 2 Loading/unloading time are approximate. It varies for each model to be installed.

# Gantry Loader 2





			GR-201 High-Speed		GR-2	01	
<b>*1</b>		Unit	1kg	3kg (op.)	1kg	3kg (op.)	
Speed							
Loading/Unloading	g time *2	sec	3.2/4.0	6.0/6.5	6.0/6.0	8.0/8.0	
Hand							
Workpiece	Flange		Ф20~ Ф60	Φ20~ Φ80	Ф20~Ф60	Φ20~ Φ80	
diameter	Shaft	mm	Φ15~ Φ	<b>p</b> 30	Φ15~ Φ	030	
Workpiece length	Flange		20~50	20~75	20~50	20~75	
workpiece tength	Shaft	mm	35~20	00	35~20	00	
Hand turning	Flange		1.8sec/	270°	1sec/9	90°	
nanu turning	Shaft	-	* Varies depending on specifications.		1.2sec/180°		
Hand back turning					-		
Workpiece weight	Flange	ka	1.0×2	3.0×2	1.0×2	3.0×2	
Workpiece weight	Shaft	kg	1.0×	2	1.0×2		
Jaw stroke	Flange		Ф12		Ф15		
Jaw Stroke	Shaft	mm	Ф25		Ф25		
Work Stocker List							
		WS-221	0	Ō	0	Ō	
84. Ibi I I		WS-231	0	0	-	-	
Multi-layer work stoo	.ker	WS-442W					
		WS-445W			-	-	
		WS-121			0	0	
C:	al. a.	WS-122			0	0	
Single-layer work sto	cker	WS-124			0	0	
		WS-132	-	-	-	-	
HAKO-BEI Rail extension is required when B type is selected.		type is	0	0	0	0	

Gantry Loader Installation table	GR-210 High-Speed	GR-203 High-Speed	GR-201 High-Speed	GR-210 NEW	GR-203 11	GR-203	GR-201
SC-100			0				
SC-200II		0					
SC-200IIL		0					
SC-300ll	0						
TW-8						0	
WT-100							0
WT-150ll		0					
WT-250ll				0	0		
WT-300	0						
WY-100V		0					
WY-150V		0					
WY-250L				0	0		
NTY <sup>3</sup> -100V		0					
NTY3-150		0					
NTY <sup>3</sup> -250				0	0		
JX-250	0						









# Gantry loader loading/unloading type

Standard, Left side, Right side, Left extension, Right extension, Passing.

\* However, there are restrictions depending on the machine model and specifications.

# Standard / Left side

NTY<sup>3</sup>-100 + GR-203 High-Speed



# Right side / Extension

TW-8 + GR-203



\* Right side, chip conveyor is rear discharge type.

# WT-100 + GR-201

Passing



\* Passing, chip conveyor is rear discharge type.

<sup>\* 2</sup> Loading/unloading time are approximate. It varies for each model to be installed.

# **Compact Loader**



MX-100

\* The combination of transfer devices is limited to IN conveyor/OUT conveyor, IN conveyor/OUT chute, and transfer device (material/finished part).

WY-100II / NTY<sup>3</sup>-100 WY-150 / NTY<sup>3</sup>-150

\* Loading/unloading times are for reference only and may vary depending on

			Compact Loader	Stan	dard		nm (op.)	Standard	extended by	Standard	extended by	
		Unit	servo	3kg	5kg (op.)	3kg	5kg (op.)	1	150mm (op.)		150mm (op.)	
	Diameter	mm	φ20~ φ130		φ32~	φ110		φ32^	- φ100	φ32~	φ100	
Workpiece Size	Length	mm	20~110		20~	100		20-	~100	20~	-100	
	Weight	kg	3.0×2	3.0×2	5.0×2	3.0×2	5.0×2	3.	0×2	3.0	)×2	
Z-axis Travel	Drive	-	Servomotor		Servoi	motor		Servo	Servomotor		Servomotor	
ız-axis iravei	Stroke	mm	2,580	1,9	910	2,0	060	1,955	2,105	2,105	2,255	
Arm Advance/Retract	Drive	-	-	Servomotor			Air c	/linder	Air cy	vlinder		
Arm Advance/Retract	Stroke	deg.	-	52					50	5	50	
	Drive	-	Servomotor	Servomotor				Air c	/linder	Air cy	vlinder	
Hand Up/Down	Stroke	mm	420	185				1	50	1	50	
	Drive	-	Air cylinder	Air cylinder				Air c	/linder	Air cy	vlinder	
Hand Swing	Stroke	٠	90°		90	0°		9	10°	9	0°	
	Speed	sec./90°	2		1.7				.7	1	.7	
	Drive	-	Air cylinder		Air cy	linder		Air c	/linder	Air cy	vlinder	
Hand Stroke		mm	32 (±16)		12 (±6.0)			15 (	±7.5)	15 (	±7.5)	
Loading/Unloading Tin	ne	sec	7.6/7.5	4.8/4.2	7.6/6.4	4.8/4.2	7.6/6.4	6.5	/6.5	6.5	/6.5	
Transport Device	Loading/		Conveyor/ Conveyor	Conveyor/ Conveyor	Conveyor/ Conveyor	-	-	Conveyor/ Conveyor	-	Conveyor/ Conveyor	-	

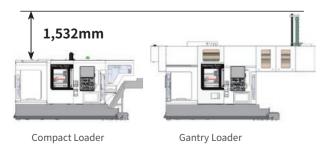
WY-100V / NTY3-100V

# Space-saving, Multifunctional **Automated System**

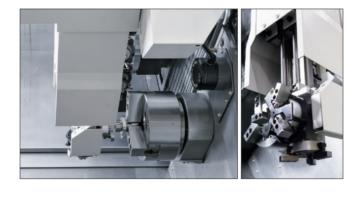
"Compact Loader" developed with an emphasis on "Spacesaving" is a transfer device that performs loading/unloading inside the machine.

The machine height is the same as that of standard machines, which has the advantage of being less subject to factory height restrictions.

# Compact Loader Height Comparison(WY-150)

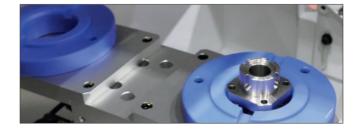


# "Compact Loader" Internal conveyor system



# **Transport Device**

Transfer/Conveyor/Chute type is selectable.



# Shaft Loader/Unloader

Loading and Unloading of shaft work is fully automated by installing a set of ZEN-BEI and HAI-BEI. Our original automation equipment contributes to the improvement of customers' work efficiency.

### Shaft Loader ZEN-BEI

	Unit	SL08W-800	SL10W-1000	SL20W-1000
Push rod stroke		1,730	1,730	1,790
Workpiece diameter( $\phi$ )×Length		φ10~φ34×100~800	φ10~φ42×100~1,000	φ10~φ51×100~1,000
Push rod bar, A size workpiece length	mm	100~500	100~400	100~400
Push rod bar, B size workpiece length	mm	500~800	400~700	400~700
Push rod bar, C size workpiece length		-	700~1,000	700~1,000
Number of workpiece stock capacity	-	23	23	23
Loading time	sec	7	7	7
Machine Dimensions (L×W×H)	mm	2,135×879×1,151	2,135×879×1,176	2,235×879×1,269



### Shaft Unloader HAI-BEI

	Unit	SU08W-800	SU10W-1000	SU20W-1000
Pull out bar stroke	mm	1,830	1,830	1,950
	mm	φ12~φ34×100~800	φ15~φ42×100~1,000	φ15~φ51×100~1,000
Pull out bar, A size workpiece length	mm	100~500	100~400	100~400
Pull out bar, B size workpiece length	mm	500~800	400~700	400~700
Pull out bar, C size workpiece length	mm	-	700~1,000	700~1,000
Number of workpiece stock capacity	-	20	20	20
Max. workpiece weight	kg	8	8	8
Unloading time	sec	7	7	7
Machine Dimensions (L×W×H)	mm	2,529×680×1,178	2,529×680×1,203	2,649×680×1,296



# Plug One

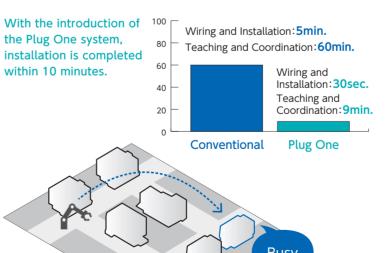
One-touch connection system for one-touch connection and disconnection of machines and robot, robot and work stocker.

Can be connected to busy

machines according to

production schedules

- This is a new style of automation proposed by Nakamura-Tome to solve these problems:
- "The installed automation system is not operating well due to fluctuating demand."
- "Robotic systems require safety fences, and the systems are large and take up a lot of space."





# One-touch

a connection unit that used, so safety fences layout of the machine consolidates electrical are not required.

to respond to demand

0 S

0

≥

### Multi-layer work stocker



### [GR-203 High-Speed] [GR-203II] [GR-201 High-Speed] [GR-201]

011 2011	iigii opecaz tok zoz	-1
WS-221	Type	Multi-layer Pallet
<b>*</b> 1	Workpiece diameter	φ15~φ100mm
	Number of pallets	10
	Stack height	300mm
	Max. loading weight	18kg/Pallet

WS-231	Type	Multi-layer Pallet
*1	Workpiece diameter	φ20~φ150mm
	Number of pallets	10
	Stack height	300mm
	Max. loading weight	32kg/Pallet

# [GR-210 High-Speed] [GR-210NEW]

WS-442W	Type	Multi-layer Pallet
<b></b> *2	Workpiece diameter	φ20~φ220mm
	Number of pallets	20
	Stack height	450mm
	Max. loading weight	40kg/Pallet
WS-445W	Туре	Multi-layer Pallet
<b>*</b> 2	Workpiece diameter	φ20~φ220mm
	Number of pallets	14
	Stack height	450mm
	Max. loading weight	40kg/Pallet

# Single-layer work stocker



# [GR-203 High-Speed] [GR-203II] [GR-201]

VS-121	Type	Single-layer Pallet		
	Workpiece diameter	φ20~φ80mm		
	Number of pallets	30		
	Max. loading weight	2kg/Pallet		
VS-122	Type	Single-layer Pallet		
	Workpiece diameter	φ20~φ80mm		
	Number of pallets	60		

	Max. loading weight	2kg/Pallet
WS-124	Type	Single-layer Pallet
	Workpiece diameter	φ20~φ80mm
	Number of pallets	120

Max. loading weight 2kg/Pallet

# [GR-203 High-Speed] [GR-203II]

	0 -1 1											
WS-132	Туре	Single-layer Pallet										
	Workpiece diameter	φ20~φ150mm										
	Number of pallets	20										
	Max. loading weight	10kg/Pallet										

- \*1 GR-201 is only available with WS-221.
- \*2 There are 2 loading stations to shorten outboard service time.

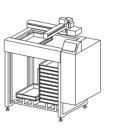
If jigs are required, a meeting and a separate estimate will be

### Work Stocker "HAKO-BEI"









			Unit	B2 Type	C2 TYpe	HAKO-BEI Link	D Туре								
	Mach	ine dimensions	mm	1,385×1,020×1,342	1,385×1,215.5×1,630	1,466×1,750×1,523	1,673×1,152×1,675								
ရွ	Tray ex	change method	-		Pass-thro	ough type									
Genera	Loading o	apacity on tray	kg	150	150	200	150								
ral		Total weight	kg	200	215	215	100								
	Workpiece	loading height	mm		960 from th	ie floor level									
	Tray external	9 tier	mm		W600× D	440× H79									
Tray	dímensions	4 tier	'''''	W600× D440× H150											
	Т	ray limit weight	kg	15 (Heavy duty sp	ecification: 15-20)	20	15 (Heavy duty specification: 15-20)								
	Shuttle (Built-in)	Drive	-	AC servomotor	AC servomotor	AC servomotor	Special feed control								
	Shuttle (Built-iii)	Stroke	mm		50	500									
	Tray up/down	Drive	-												
	drive	Stroke	mm		76	59									
		Robot	-	_	1-axis (1-axis servo)	2-axis (2-axis servo)	2-axis (HAKO-ROBO)								
Drive	X-axis	Drive	-	_	_	_	AC servomotor								
Axis	A-axis	Stroke	mm	_	_	_	650								
ŝ	Y-axis	Drive	-	-	AC servomotor	AC servomotor	AC servomotor								
	1-dxIS	Stroke	mm	_	850	1,300	500								
		Drive	-	_	Air cylinder	AC servomotor	Air cylinder								
	Z-axis	Stroke	mm	-	175	200	150								
		Carrying load	kg	_	0.3	1	0.3								
	Loading/unloa	ding cycle time	S	-	8~20	8~20	8~20								
	Tray exchange time			·	3	50	·								

# Please select from the following specifications for bar feeders.

Work Rest

This is required when bar feeder is equipped.

Workpiece

Parts Catcher

ejecting device



Parts Catcher | Shaft Unloader

Gantry Loader

A Parts catcher is a device to unload finished parts into a bucket and brings them out of the machine.

Parts catcher specifications such as Maximum part diameter × Length × Weight vary from one model to another. (\*1) If anti-scratch measures are required for finished parts for quality, select Parts catcher type G or Turret Servo Gripper type that grasps the workpiece by hand or a Gantry Loader+HAKO-BEI instead of the Parts catcher type A, drop type.

- \*1 Custom orders outside the standard specifications may also be available. Please ask our distributors for details.
- \*2 A workpiece discharge confirmation device is required for drop type unloaders.

# Parts catcher type A (Bucket type)

When a larger spindle's bar capacity is selected, a parts catcher with larger specifications is to be selected accordingly. (op.)



# Part catcher type G (Gripper type)

It unloads the finished parts from R-side chuck. It is a one-gripper type parts catcher. The finished parts are pulled out by moving the R-spindle.



### Turret Servo Gripper type

The milling motor can be used as a drive source to control the gripping force through torque control.



### This is required when Parts catcher A or B is equipped

Parts ejector and Parts eject checker

# Pneumatic parts ejector (Recommended) The finished parts are ejected

with a pneumatic cylinder It includes parts ejection confirmation. Two limit switche are equipped on both stroke ends of the pneumatic cylinde one on the front end, and on on the back end. Part ejecti is confirmed when the switch the forward end is turned ON An ejecting head correspo to the workpiece diameter a shape is necessary. (Engineering arrangement for each part is side spindle necessary).



Air-blow through the right hand

# Parts ejector spring type

The finished parts are eiected by spring force. An ejecting head corresponding to the workpiece diamete and shape is necessary. (Engineering arrangement for each part is necessary) Ejecting heads with air blow noles are also available. In this case, air blow through the spindle (op.) is necessary.

# Parts eject checker (necessary)

It prevents collision by mistake during workpiece We can offer two kinds of parts confirmation:

1. Check if there is a workpiece in the L-side chuck 2. Check if the finished part was ejected from the R-side chuck





Detect no workpiece 2. Workpiece eject detectio

### Parts eject checker is necessary when parts eiect conveyor is equipped.

Parts outlet Door pocket shape

# Stocker type

The finished parts are stocked into a door mounted box.



# Outlet chute type (Recommended)

The finished parts are unloaded through the door onto a conveyor or a bucket. To prevent scratching the finished parts during unloading, a conveyor is recommended. (op.)

To prevent scratching the finished parts during unloading, additional plastic plates on the chute can be specified.



# Control(1)



# **NT Thermo Navigator Al**

**Acquired Data** 

Thermal Growth Compensation using Al.

② Measured Dimensions 3 Retrieval of Wear Offset Data



Compensation model built using Al machine learning.





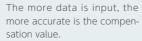
# Powered by Al

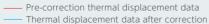
Time and measured dimension data are input into a dedicated AI Learning software, to build an optimized thermal growth compensation model.



# High Precision Thermal Growth Compensation

The compensation value is calculated from acquired data.





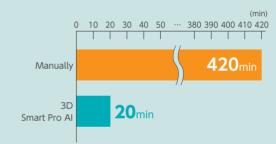
# 3D Smart Pro Al Al Analysis NC Programming Support Function

This function analyzes 3D CAD model data and generates an NC program for processing from blank to finished parts. Simply follow the displayed guidance and enter the required information to create the program.





It drastically reduces man-hours required for creating NC programs and improves set up and production efficiency.



\* NC programming level : Beginner engineer

# **Transfer Setting Tolerance Setting**

Once the transfer position is set, the machining area and transfer program are created.



Once the tolerance value is

input, the target value for

machining can be set.

**Optimization of Machining Processes** In addition to defining the required machining processes, Al proposes a suitable machining process sequence.



### **Tool Guide**

If the tool configuration is incomplete, the AI analyzes the CAD model data and provide the necessary tool information.



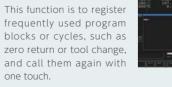
# Digital Chuck Interlock

Set the Chuck Open and Close detection position easily.

The chuck open / close position is set on the NT SmartX screen

Setup time and machining cycle time are reduced.







Reduce programming and setup time, while eliminating input errors.



# Control<sup>2</sup>

# NT Manual Guide i ~IUCK-BFI II ~

# It helps to make NC programs (ISO/EIA G-code programs) used in a machining process program.

generate NC programs (ISO/EIA G-code programs) easily. Processes created in conversational mode can be cut, copied or pasted ensuring flexibility. Additionally, tool-path simulation or solid-model animation. several cycles such as part-transfer cycle, requiring

A programming guidance system with the ability to waiting M-codes, are readily made with the "NC program editing support function". The "NC program simulation function" can be used to check created- programs by



By selecting the material, cutting conditions are automatically input.



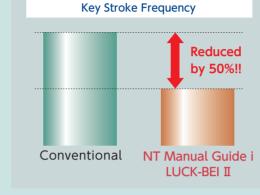
By selecting the material, cutting conditions are automatically input.

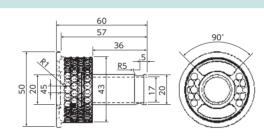


Cutting conditions End mill

# **Automatic Cutting-Condition Setting Function**

By setting the material type and required surface roughness, cutting conditions are automatically generated. These can be also changed depending on customer's experience.



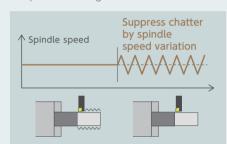


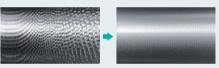
By introducing the "automatic cutting condition setting function", the number of key strokes required to make a program were reduced by 50% reduced, compared with the previous NT Manual Guide i version.

# **Chatter Canceller**

Reduce the chatter and vibration by automatically changing the spindle speed up/down continuously during cutting. The function can be easily turned on with the M-code, and the amplitude and frequency can be set arbitrarily.

- \* It does not guarantee that the function works without chatter and vibration.
- \* Chatter and vibration reduction depend on the setup and the cutting condition.





Oscillation Cutting (op.)

By oscillating the tool for a certain period,

the chips are cut into small pieces. It can

be activated easily by using a simple

FANUC G-code and resolve workpiece

damage issues caused by chips twined

# Double safety features for maximum protection

NT Machine Simulation / NT Collision Guard + Airbag (Overload detection)

The machine comes protected with dual safety features: "NT Machine Simulation/NT Collision Guard" to prevent a collision beforehand, and the "Airbag Function" minimizes damage to the machine in case of collision.

# Airbag (Overload detection)

The software's barrier system is not foolproof. Making a data input mistake will result in a machine collision. However, Nakamura-Tome machines will not break even after the machine collision.

# When the machine collides, there is no reason to panic.

The Airbag (Overload detection) of the machine tool significantly reduces the impact of a collision and protects the machine.

> Barrier? Even with barrier function, machine collisions may occur





**▲**Video



Crash? Within one millisecond after a collision, the servo motor direction is reversed, and the machine stops in EMG mode

Material: Aluminum

around the part.



Cutting speed: 200mm/min Cutting depth: 1.0mm

Cutting feed: 0.1mm/rev

### NT Machine Simulation

# Machine collisions are avoidable with Preventive safety technology! Interference checks can be carried out based on the machining paths

obtained from the NC program. By simulating machine operations before starting machining, it is possible to reduce the risk of stop just before the collision. machining errors and interference.



Image shown here is of a 2-turret machine

# imulation is performed while checking the amount and modal

nformation.

It is possible to override the settings or rapid and cutting eed individually Additionally, simulatio by process or by singl lock is possible

By process

# **NT Collision Guard**

NT Machine Simulation is synchronized with the machine operation, allowing the machine to be operated while performing interference checks. Available in automatic and manual mode. If interference is detected, the machine will



Image shown here is of a Tool spindle machine

# With Airbag Retraction within 0.001 sec

\* It is not a function that guarantees the prevention of machine break This function does not eliminate the impact on the machine.

# Control3

# NT NURSE

\*Depending on machine specifications, some functions are not available.

All-in-one software! NT NURSE is software that provides the operator with user-friendly support for operation, programming and production on the machine. Among vital features are phase recognition (a must for multitasking), direct chucking to prevent positioning error during transfer, and perfect synchronization of the left and right hand spindles. Among other

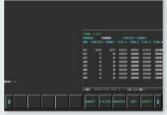
features, are the load monitor for detecting tool wear and tool breakage, tool life management, operation condition monitoring, in addition to many other features to simplify programming, set up, operation and production, all offered in one single

# **Useful functions**





Tool Counter



Menu Screen

Tool Life







Energy Saving

Operation Condition of each Tool

Operation Message

Quick Offset

# NT WORK NAVIGATOR



No fixtures required Machining parts with non-round shapes, such as forgings or castings require that the raw part coordinates be recognized by the CNC control. It works just by touching the part with a simple inexpensive probe (mostly a round bar mounted on a tool holder) and using the torque control feature of the servo-motor, which is to record required coordinates in the CNC.

The NT WORK NAVIGATOR is eliminating the need for positioning fixtures and special clamping devices.



# **NT Smart Sign**

# Nakamura-Tome IoT software

# Monitoring



Real Time Monitoring of machine running conditions, in addition to visualizing alarm history and past events.

# ■ Data Input/Output



Input and output programs tool data and other machine data from the monitoring P

Diagnosis



Diagnose problems with the machine servo drives and spindle drives, using a dedicated program.

# NT Update

\* Please check Nakamura-Tome website for the countries where this service is provided.

Visualize

Web site of Nakamura-Tome Exclusive membership. The necessary software can be downloaded and update your machine's software to the latest version.

Just register as a user on the membership website and start using the service right away.



Scan here to register as a user ▶

# 1 Registration

Enter user and machine information on the membership website.



# 2 Download Software

Enter the issued user ID and password

Download the software in the membership website



# 3 Software Update

Save the installer to USB and insert it into the machine.

Put the machine in emergency stop and execute Setup.bat in the USB to install the following software.

NT-IPS NT NURSE NT Collision Guard NT Manual Guide i

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# NC specification chart / All models

			Control		1001	0564		<u>_</u>			/ Number of registrable progra									Numb	er of tool offset							chining s		т —	
ption:		Control	нмі	Display	128kbyte (320m)		512kb (1280			byte 60m)			lbyte 20m)	_	4Mb (1024	<u> </u>		byte l80m)		Standard			Option		N T	N T	N T WORK	Δirhaσ	NT-MGi	Chatter	Oscillati
ption.	Model	FANUC	NT SmartX	Standard	250	500				000 200	0 400	<del>,                                    </del>		4000	1000			4000		*2		99	200	999	Guard	NURSE	NAVI	Allbag	N1-MGI	Canceller	
	JX-200	31i-B5 Plus (2-PATH)			_	-	-	_   .	_   .	-   -	-	_	-	_	_	std.	_	•	ATC 40 300+99	ATC 80 300+99	ATC 120 300+99	-	_	•							
ATC series	Standard	31i-B5 (2-PATH)			_	-	_			– sto	ı. –	_	_	•	-	•	_	•	ATC 40 99+99	ATC 80	ATC 120 )+99	-	_	•							
Tool spindle + Lower turret		31i-B5 (3-PATH)		19"	-	_	-		_   .		_	-	-	std.	_	•	_	•	ATC 40 200+99+99	ATC 80	ATC 120 300+99+99	-	-	•							
Eower turiet	MX-100	31i-B5 (2-PATH)	std.	color LCD touch panel		-	-	_   .	-   -	– sto	ı. –	-	-	•	-	•	-	•	ATC 36	ATC 48	ATC 72 300+99	-	-	•	std.	std.	std.	std.	std.	std.	
ATC	Standard Standard	24: DE						-1-1											ATC 40 99	ATC 60·80	ATC 120 200	1									
series	NTRX-300 / 300L Sub spindle(op.)	31i-B5			_	_	_	std.		•	_	_	•	•	•	•	•	•	ATC 40 99	ATC 60·80 200	ATC 120 400	-	•								
	NTY <sup>3</sup> -100V	31i-B Plus (3-PATH)			-	-	-	_   .	-   -	-   -	-	-	-	-	std.	•	•	•													
NTY <sup>3</sup> series	NTY³-150	31i-B	std.	19" color LCD touch panel				ctd	_							•				99+99 + 99				•	std.	std.	std.	std.	std.	std.	
	NTY³-250	(3-PATH)		touch punct				std.																							
	WY-100V	31i-B Plus (2-PATH)			-	-	-		-   -	-   -	-	-	-	-	std.	•	•	•													
W Y series	WY-150V	32i-B Plus (2-PATH)	std.	19" color LCD touch panel		-	-			-   -	_	-	-		std.	•	•	•		99+99				•	std.	std.	std.	std.	std.	std.	
	WY-250L	32i-B (2-PATH)			_	std.	-	•	-   (	• •	_	_	•	•	•	•	•	•													
	NT-Flex	Oi-TF Plus (2-PATH)		15" color LCD touch panel		-	-	_   -	-   -	-   -	-	-	-	-	std.	_	_	•		99+99		_	_	_	-	std.	std.	std.	std.	std.	
	WT-100			touch paner																											
W T series	WT-150 II	32i-B (2-PATH)	ctd	19"		ctd														99+99					ctd	ctd	ctd	ctd	ctol	ctd	
	WT-250 II	(2-PATH)	std.	color LCD touch panel		std.			-   '	•						•	•			99+99		_			std.	std.	std.	std.	std.	std.	
	WT-300																														
B-axis	NTJ-100	31i-B	std.	19"																00100				•	-4-1		-4-1	-1-1	-1-1		
series	Super NTJ	(2-PATH)	_	color LCD touch panel						– sto			-		_	•				99+99				-	std.	std.	std.	std.	std.	std.	
T W series	NEW TW-30	32i-B (2-PATH)	std.	19" color LCD touch panel	) –	std.	-	•	- (	• •	_	-	•	•	•	•	•	•		99+99		-	-	•	std.	std.	std.	std.	std.	std.	
	SC-100X <sup>2</sup>			15" color LCD touch panel			-	_   .	_   .	-	-	-	std.							99+99		_	_						std.	std.	
	SC-100 Standard Sub spindle(op.)			15" color LCD			std.			-	•	-	•							99		_	•						•	std.	
	SC-200I / 200I L	Nakamun					_				-	_	std.							99		_	•						std.	std.	
S C series		Nakamura- Tome FANUC		15" color LCD touch panel	o   -	-			+	-					-									-		std.	std.	std.		-	
	AS-200 / 200L Standard						std.			-	-	<del>-</del>   -	std.							99		-	-						std.	std.	
	SC-300 II / 300 II L Sub spindle(op.)			15" color LCD				_ st	td. (	•	Ė	•	•							99		-	•						•	std.	
	SC-450L Standard Sub spindle(op.)			10.4" color LCD		std.			std		-	+-	<del>-</del>							64		•							•		

# Lineup Multitasking Machine



### Automation





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