





## **Deburring Center**

# Deburring Center



### Mechanizes manual deburring of die casting material in variable-type variable-volume production

Deburring of die casting material in variable-type variable-volume production is currently performed manually, since using a robot system for this operation is inefficient.

Due to problems such as operator shortages and difficult work environments, the need for mechanization has increased.

The DG-1 Deburring Center has deburring setup functions achieved by Brother's original technology to enable mechanization of manual deburring.

Die casting parts manufacturing processes



#### Target burrs

Parting line (Flash)



Ejector pin mark





Gap in slide





## Brother's original functions greatly improve deburring efficiency

Brother's original deburring setup functions greatly improve deburring efficiency in variable-type variable-volume production, which is currently performed manually.

#### Three features that encourage mechanization of manual deburring J

The DG-1 Deburring Center has Brother's original deburring functions. Simple teaching and correction, and automatic path creation enable fast deburring setup. Optimal machine configuration supports a variety of burr types, and achieves high chip evacuation for dry machining, which encourages mechanization of manual deburring.

#### Jig area

(reference dimensions)

Controlled by four axes, including the tilt axis (A axis) of the roller gear cam structure. Ample jig area is secured, enabling highly flexible jig design. An A-axis table (optional) is available to configure the trunnion jig between the faceplate of the tilt axis and the support.

Mounting range when A-axis table (optional) is selected

#### (1) Fast machining path creation or correction (Brother's original deburring setup functions)



(2) Supports a wide range of deburring operations

(3) High chip evacuation for dry machining







#### Jig mounting example

Waste-free machine configuration enables highly flexible jig design, making it easier to mount jigs for large workpieces or jigs for multi-part machining.



Large workpiece (size: 365 x 270 x 45 mm)



Two small workpieces



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### Great reduction in deburring setup manhours Create simple machining paths in a short time

The machine has Brother's original deburring setup functions, including easy teaching of representative points, intuitive path correction, automatic machining path creation, and automatic machining program conversion. Fast deburring setup has been achieved, enabling mechanization of deburring in variable-type variable-volume production that is currently performed manually.

## Operator

STEP1

Teaching representative points

Teaching representative points is conducted by allowing the tool to contact the master workpiece\*<sup>1</sup>. The number of teaching points is less than robots, and there is no need to define straight lines or arcs. For a gentle curve, a machining path can be created automatically by teaching only the start and end points. \*<sup>1</sup>. Please prepare a cleanly deburred workpiece as a master workpiece.



STEP2 Automatic machining path creation

The machining path is created automatically by profiling the master workpiece based on the representative points that have been taught. This requires less correction of the path than robots or machining centers.





tive points Automa

Automatic machining path creation

#### Teaching controller (optional)

Moving direction and speed can be intuitively manipulated to improve the efficiency of teaching representative points.





Based on the representative points that have been taught, the machining path is created automatically by rotating the tool and repeating contact with the master workpiece.



(2) Repeats contact for each minute line segment

(3) Automatically creates the machining path based on contact points

### Comparison of deburring setup processes

Teaching representative points, automatic path creation, and easy path correction significantly reduce deburring setup time. The machining path can be easily created by profiling the material, eliminating the need for repeated reteaching or CAD/CAM data correction as is required for robots or machining centers.





STEP3 Path correction by intuitive operation

The touch panel can be used to instruct correction points, and the machining path and conditions can be corrected by intuitive operation.

Since correction is possible for each teaching point or area, reteaching, such as required for robots, is not necessary.



Correction screen



Select teaching points/area (blue)

Correction procedure (1) Select teaching points/area you want to correct. (2) Input correction.

ation :ck	Repeated (Teaching ⇔ Operation check)	
ation :ck	Repeated (CAD/CAM ⇔ Operation check)	
ath ection	Approx. 70% less *	
perati	check	

\* Comparison of setup time using a sample workpiece



#### STEP4 Automatic machining program conversion

Automatically converts the machining path and condition data into a machining program. No programming expertise is required, enabling easy creation of machining programs. Furthermore, advanced programming with macro programs is also possible by editing the automatically created machining program.



Machining path and condition data

Machining program





Scan or Click

#### Equipped with pickup type ATC

The pickup type ATC can store six tools, and various types of deburring tools can be used. The open/close magazine cover minimizes the impact of chips.

Pickup type AT	C
Tool storage capacity : 6 tools	Tool To Tool : 3.0s

#### Function that reduces risks of machine breakage in the event of teaching mistakes<sup>\*1</sup>

A low torque function is provided to reduce the machine's travel speed and force. Even if teaching mistakes are made during teaching of representative points or automatic path creation is affected by teaching mistakes, the machine detects abnormal contact and stops.

This function is enabled by pressing the Low Torque key on the operation panel.





Pickup type ATC



\*1. This function does not prevent breakage in all collision modes

#### Chip evacuation for dry machining

The direct evacuation structure evacuates chips outside the machine. Chips can be easily disposed of by drawing the chip tray from the front of the machine.



Direct evacuation structure



Chip tray (front draw type) \*2 \*2. Can be changed to rear draw type.



Controller with a cable, used for moving axes or teaching representative points of a deburring shape. Equipped with emergency stop and enable switches.

\* A manual pulse generator option is not available.





Jig control valve unit Valve set for jig control, composed of 3 valves, 3 pressure switches, and 3 select switches. Please prepare piping separately. \* The switch panel (10 holes) is not included.



Work light (1 or 2 lamps) LED lamps are used to extend lamp life and save energy. \* The 1st lamp is installed on the front and the 2nd lamp is installed on the left inside the machine.



Signal light (1, 2, or 3 lamps) LED lamps are used. No maintenance required. Can be tilted to improve visibility

Teaching controller     A-axis table
<ul> <li>Rotary joint 6 ports</li> </ul>
<ul> <li>Jig control valve unit (3-row)</li> </ul>
•Side cover with transparent window, single side
<ul> <li>Work light (1 or 2 lamps)</li> </ul>
<ul> <li>Signal light (1, 2, or 3 lamps)</li> </ul>
<ul> <li>Automatic door with switch panel (10 holes)</li> </ul>
<ul> <li>Switch panel (10 holes)</li> </ul>
<ul> <li>Tool breakage detector, touch type</li> </ul>
<ul> <li>Spindle override</li> </ul>
<ul> <li>Specified color</li> </ul>

 Transformer box EXIO board assembly 1) EXIO board, input 32/output 32, additional #1 2) EXIO board, input 32/output 32, additional #2 PLC programming software for D00 Industrial network 1) CC-Link, master station 2) CC-Link, remote device station 3) PROFIBUS DP, slave 4) DeviceNet, slave 5) PROFINET, slave 6) EtherNet/IP, slave

•Please read the instruction manuals and safety manuals before using Brother products for your own safety.

- •This machine is exclusively for dry machining of aluminum alloy. Do not use the machine for other materials.
- Dust collectors, vacuum cleaners, and air blowers must not be used due to the risk of fire or explosion. Take adequate safety measures against fire and explosion.
- Machine life may be affected, depending on machining materials, tools, etc. For further questions, please contact our sales representative.

•Leave 700 mm between machines as maintenance space.

•When exporting our machine, the machine is deemed to be included in the "applicable listed items" controlled by the Foreign Exchange and Foreign Trade Law of Japan. When exporting the machine, please obtain required permissions, including an export license, from the Ministry of Economy, Trade and Industry (METI) or Regional Bureaus of Economy, Trade and Industry before shipment. When re-selling or re-exporting the machine, you may need to obtain permissions from METI, and the government of the country where the machine is installed.







Rotary joint

Pneumatic 6-port rotary joint built into the tilt axis. Pneumatic piping to the rear of the machine is included with this option.

it brighter, making the machining chamber easier to see. \* When needed for both sides of the machine, please order two covers.



Automatic door with switch panel (10 holes) A motor-driven door is used, achieving smooth operation.



Tool breakage detector, touch type A touch switch type tool breakage detector is available.

 Memory expansion 3 Gbytes Interrupt type macro Rotary fixture offset

#### Table details



#### External dimensions





#### A-axis table (optional)





\*1. Jig area when the A-axis table and tool breakage detector are not mounted. Please check the external views or interference diagrams provided by Brother when designing jigs or checking for interference.



#### Machine specifications

		Item		Deburring Center DG-1		
CNC Unit				CNC-D00		
	X axis		mm(inch)	500 (19.7)		
	Y axis		mm(inch)	300 (11.8)		
Travels	Z axis mm(inc		mm(inch)	275 (10.8)		
	A axis	A axis		360		
	Distance be center and	etween A -axis rotation spindle nose end	mm(inch)	80~355 (3.1~14.0)		
Tabla	Max. loadin	g capacity	kg(lbs)	50 (110)		
Table	Max. table load inertia		kg·m²(lb·inch²)	0.7 (2,392)		
Caladia	Spindle spe	ed	min <sup>-1</sup>	1~20,000		
Spindle	Tapered hole			7/24 tapered No.15		
	Rapid traverse rate (XYZ-area)		m/min(inch/min)	40 x 40 x 40 (1,575 x 1,575 x 1,575)		
Feed rate	Cutting feed rate		mm/min(inch/min)	X, Y, Z axis: 1~30,000 (0.04~1,181) *6		
	Indexing feedrate (A)		min-1	100		
	Tool shank type			JBS4002-15T		
	Pull stud typ	pe *3		JBS4002-15P (45°)		
	Tool storage capacity		pcs.	6		
ATC unit	Max. tool length		mm(inch)	150 (5.9)		
	Max. tool diameter		mm(inch)	32 (1.2)		
	Max. tool weight *1		kg(lbs)	0.4 (0.9)		
	Tool selection method			Pickup method		
Tool ahanga tima *4	Tool To Tool		sec.	3.0		
1001 change unie "4	Chip To Chip		sec.	4.3		
	Main spindle motor (continuous) *2		kW	2.1		
Electric motor	Axis feed motor		kW	X, Y, Z axis: 0.32 A axis: 0.9		
	Power supply			AC 200 to 230 V±10%, 3-phase, 50/60Hz±2%		
Dowor course	Power capacity (continuous)		kVA	3.8		
Power source	Air supply	Regular air pressure	MPa	0.4~0.6 (recommended value 0.5MPa *5)		
		Required flow	L/min	20		
	Height		mm(inch)	2,033 (80.0)		
Machine dimensions	Required floor space [with control unit door open] mm(inch)		oor open] mm(inch)	998 x 1,656 [2,494] (39.3 x 65.2 [98.2])		
	Weight k		kg(lbs)	1,200 (2,646)		
Standard accessories				Instruction Manual (DVD 1 set), leveling bolts (4 pcs.), leveling plate (4 pcs.) , Chip tray, Top cover		

\*1. Actual tool weight differs depending on the configuration and center of gravity. The figures shown here are for reference only. \*2. Spindle motor output differs depending on the spindle speed. \*3. Bother specifications apply to the pull studs. \*4. Measured in compliance with JIS B6336-9 and MAS011-1987. \*5. Regular air pressure varies depending on the machine specifications, machining program details, or use of peripheral equipment. Set the pressure higher than the recommend value. \*6. Value when using high accuracy mode B and tool center point control.

#### NC unit specifications

CNC model	CNC-D00			
Control axes	4 axes (X, Y, Z, A)			
Simultaneously controlled axes	Positioning	4 axes (X, Y, Z, A)		
	Interpolation	Linear: 4 axes (X, Y, Z, A)		
		Circular: 2 axes		
		Helical/Conical: 3 axes (X, Y, Z)		
Least input increment	0.0001 mm, 0.00001 inch, 0.0001 deg.			
Max. programmable dimension	±999999.9999 mm, ±99999.99999 inch			

#### NC functions

Operation	Dry run		Tool center point control		PROFIBUS DP, slave	NC language	Menu programming
	Machine lock		(Look-ahead 1,000 blocks)		DeviceNet, slave	functions	Local coordinate system
	Program restart	Monitoring	Low torque function		PROFINET, slave		Expanded workpiece coordinate system
	Rapid traverse override		Overload prediction		EtherNet/IP, slave		One-way positioning
	Cutting feed override		Waveform display / Waveform	Energy saving	Automatic power off		Inverse time feed
	Background editing		output to memory card		Standby mode		Programmable data input
	Screen shot		Production performance display		Automatic work light off		Tool length compensation
	Operation level		Tool life / Spare tool	Support apps	Deburring program		Cutter compensation
	External input signal key	Maintenance	Status log		Adjust machine parameters		Scaling
	Shortcut key		Alarm log		ATC tool		Mirror image
	<0ptional>		Operation log		Tool life		External sub program call
	Spindle override		Maintenance notice		Waveform display		Macro
Programming	Absolute / Incremental		Motor insulation resistance measurement		Production performance		Tape operation / FTP load operation
	Inch / Metric		Battery-free encoder		Power consumption		Multiple skip function
	Coordinate system setting		Brake load test		Recovery support		<0ptional>
	Corner C / Corner R	Automatic /	Computer remote		Inspection		Interrupt type macro
	Rotational transformation	Network	OPC UA		PLC		Rotary fixture offset
	Subprogram		Auto notification	Accessories	File viewer		
	Graphic display		Built-in PLC (LD/ST/FBD)		Notebook		
High speed and	High-accuracy mode AIII		<0ptional>		Calculator		
high accuracy	High-accuracy mode BI		CC-Link, master station		Register shortcut		
	(Look-ahead 160 blocks)		CC-Link, remote device station		Display off		

\*2. Dimensions when the A-axis of the A-axis table (optional) is at 0 deg.

500 Mbytes, 3 Gbytes (optional) (Total capacity of program and data bank)			
USB memory interface, Ethernet			
4,000 (Total capacity of program and data bank)			
NC language			

\* "Control axes" and "Simultaneously controlled axes" indicate the maximum number of axes

 $^{\star}$  Ethernet is a registered trademark of Xerox Corporation in the United States.

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Figures in brackets () are the country codes.

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#### https://machinetool.global.brother/

Specifications may be subject to change without any notice.

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