



2 modules unit
Machine width : 900 mm



4 modules unit
Machine width : 1,800 mm



8 modules unit
Machine width : 3,600 mm



DLFn

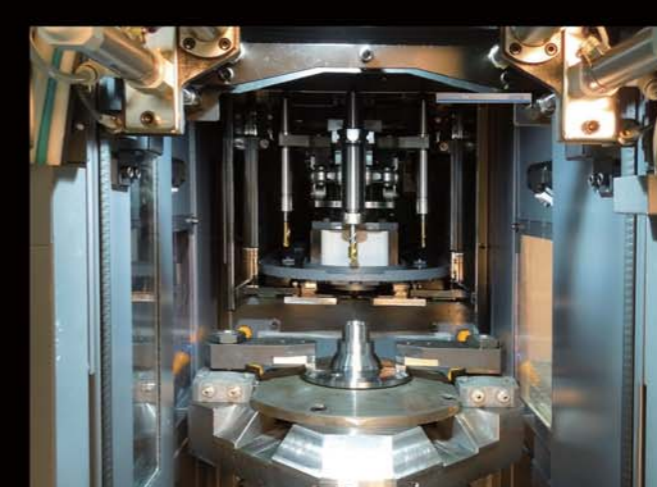
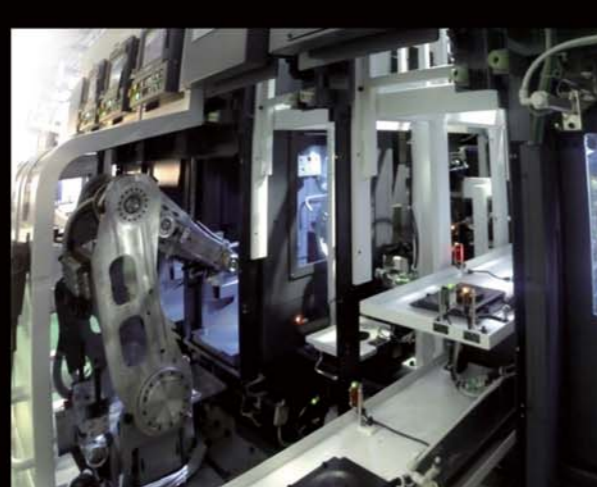
Modular production equipment

PARADIGM SHIFT

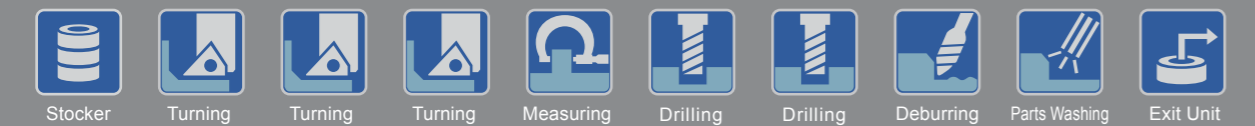


The Revolutionary DLFn - Modular Machining
Has Never Been So **Flexible** and **Fast**.

DLFn
Modular production equipment

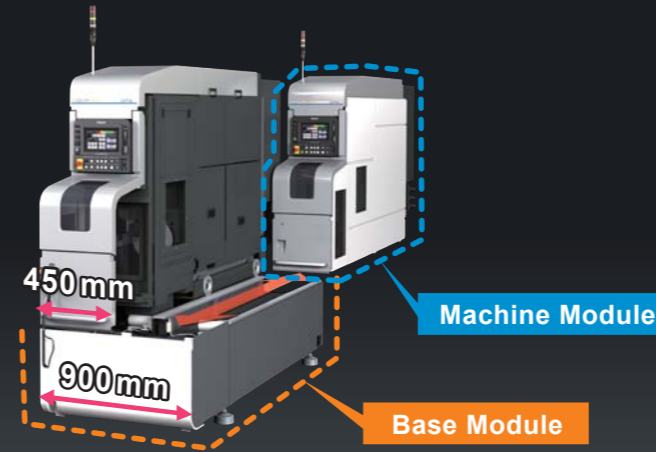


**Minimize Production Floor Space
Enhance Flexibility and Efficiency**



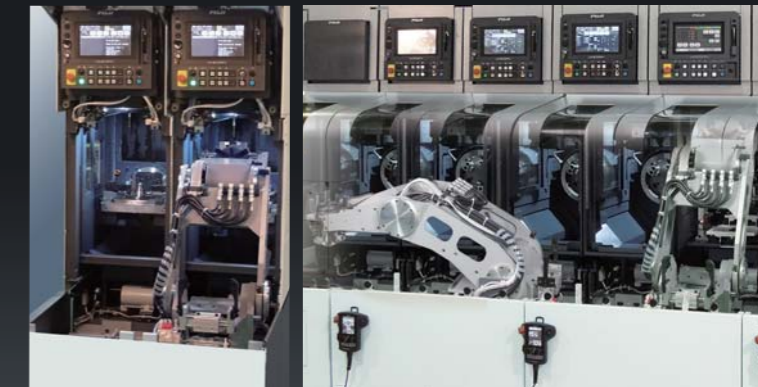
Module

Two modules can be set on one base.
You have flexible processing on the standardized bases.

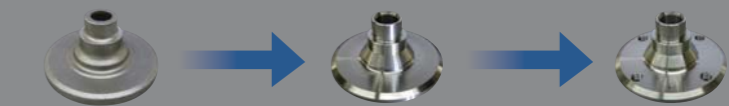
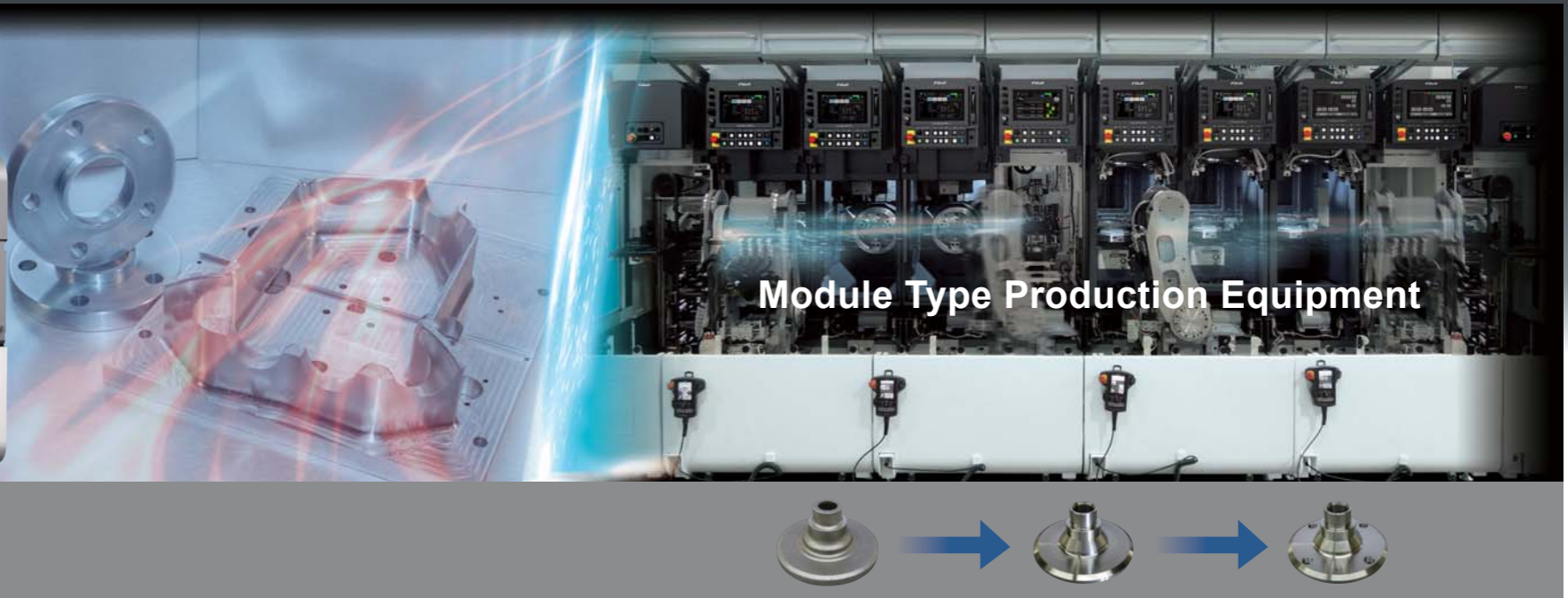


Automatic work conveyance

Internal work handling units allow fully automatic line configuration.
Work removal is performed in 5.8 seconds reducing.

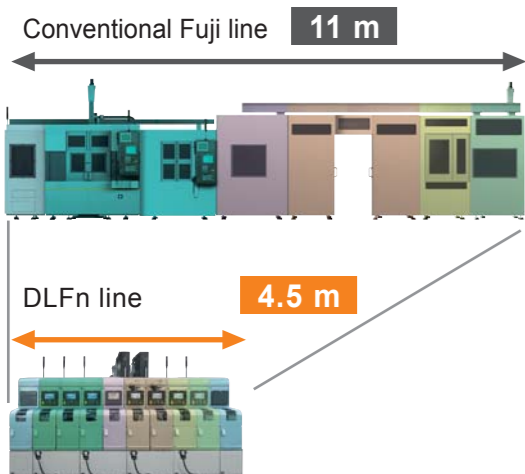


5 axes robot



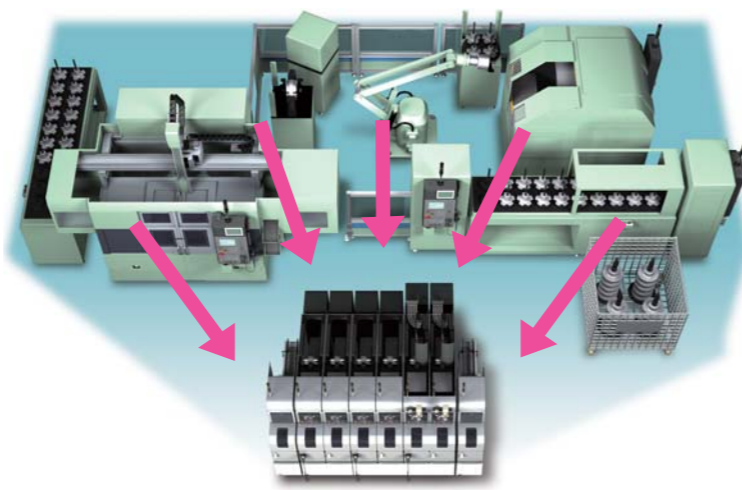
Entire line length reduced by 50%

Production is possible in less than half of the space required by current Fuji mode.



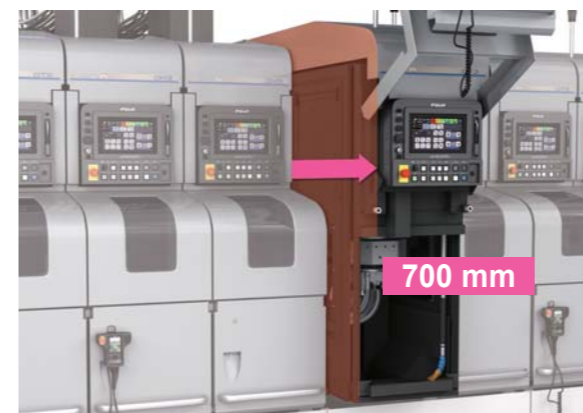
Improve productivity

Save the production space with DLFn



Modules can be pulled forward

Individual modules are capable of being pulled forward 700 mm allowing ease of changeover and maintenance.



Controller UNICORN

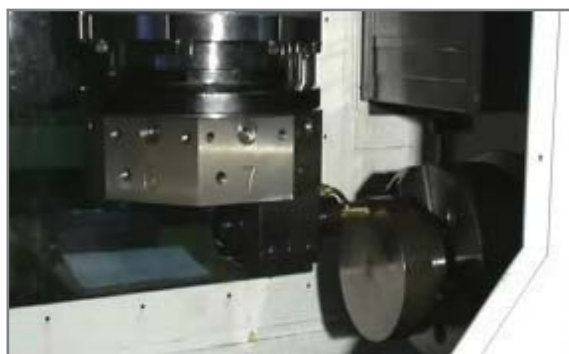
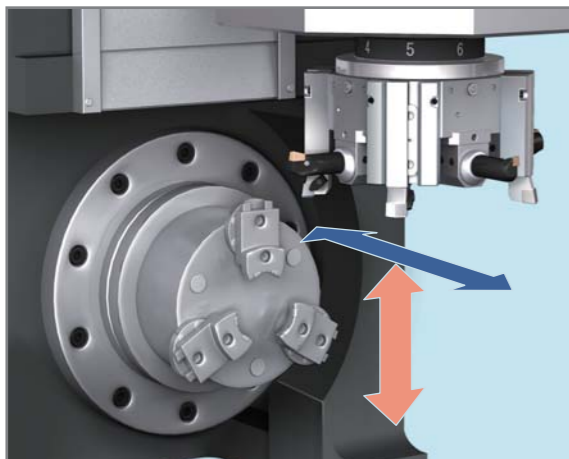
This is Fuji's original control unit. Machines, conveyance units, and peripherals are controlled by UNICORN.

Each module is uniformly operated by UNICORN. Easy to operate and use.





Rigid Compact Machine – The New Norm



Cutting Capacity (DT3, 7.5/11kw)

Max.O.D. cutting stock **7.5 mm**

Material	Cutting speed	Feed speed
S45C	150 m/min	0.3 mm/rev

Max.Grooving width **11 mm**

Material	Cutting speed	Feed speed
S45C	100 m/min	0.1 mm/rev

Live Tool Specification (Live Tool Turret 0.75kw)

Drill Max. cutting dia **φ8**

Material	Cutting speed	Feed speed
S45C	55 m/min	0.1 mm/rev

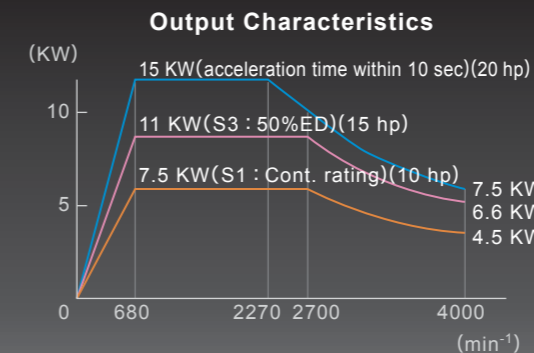
Tapping Max. cutting dia **M8**

Material	Cutting speed	Feed speed
S45C	10 m/min	1.25 mm/rev

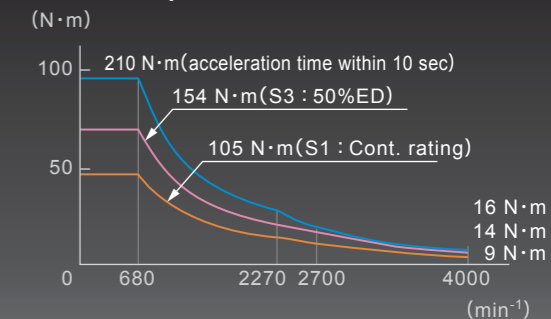
The above-mentioned data is actual values, but not a performance guarantee.

Spindle Output Characteristics

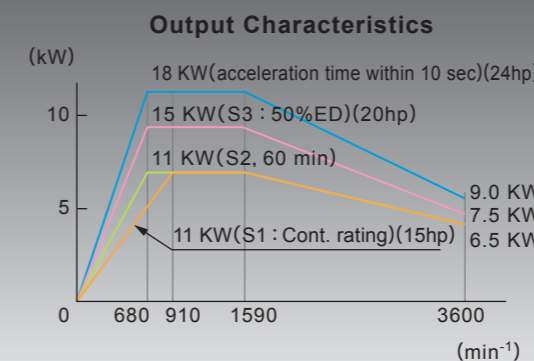
7.5 / 11kw



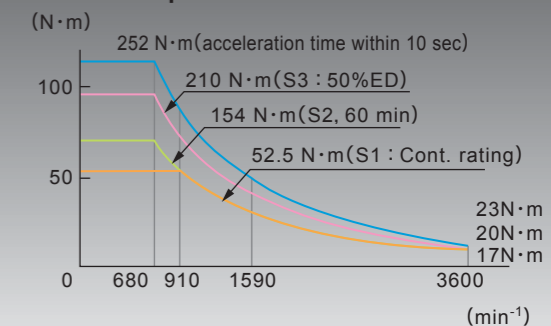
Torque Characteristics



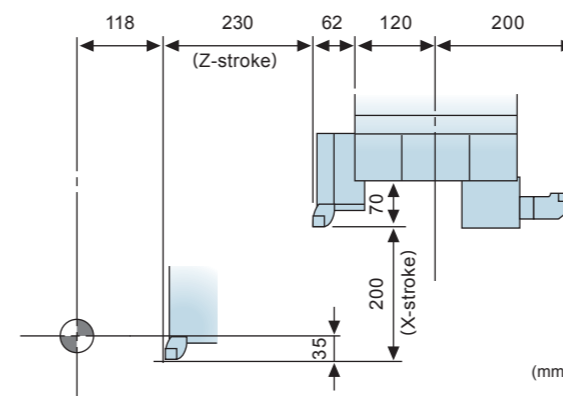
11 / 15kw
(Global Spec)



Torque Characteristics



Tools Traveling Range



Option

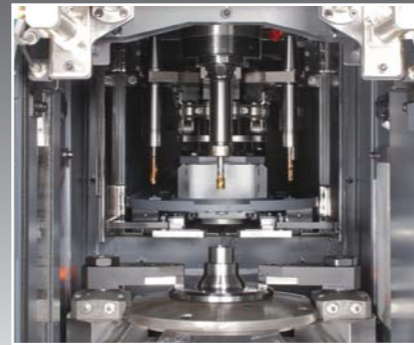
- Through Spindle Coolant
- Air Confirmation
- Tool Detector
- Work Pusher



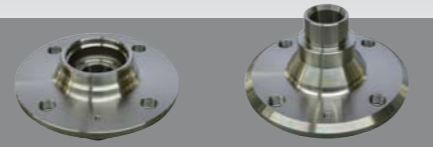
Tool Detector

Module Specifications

Item		DT2	DT3	DT4
Max. Part Size	mm [inch]		φ200 [φ7.87]	
Max. Swing	mm [inch]		φ310 [φ12.2]	
Spindle diameter	mm [inch]	φ80 [φ3.15]	φ100 [φ3.94]	φ120 [φ4.72]
Spindle Nose		A2-5	A2-6	A2-8
Spindle Bore	mm [inch]	φ47 [1.9]	φ56 [2.2]	φ67 [2.6]
Spindle Motor	KW [hp]		7.5 [10] / 11 [15]	
Spindle Speed	min ⁻¹	Max. 4,300	Max. 4,000	Max. 3,000
Spindle Motor (Global Spec)	KW [hp]		11 [15] / 15 [20]	
Spindle Speed (Global Spec)	min ⁻¹		Max. 3,600	Max. 3,000
Number of stations	tools	8		
Cutting Tool		Square Shank □25 Boring Bar φ32		
Cutting Tool (option)		Capto (Type-C4)		
Chuck Size	inch	6~8	8~10	8~12
Slide Stroke	mm [inch]	X-axis : 200 [7.87] Z-axis : 230 [9.06]		
Rapid Traverse	m / min	X-axis : 24 Z-axis : 24		
Feed Setup Unit	mm	X-axis : 0.001 Z-axis : 0.001		
Module Weight	kg [lb.]	2,000 [4,400]		



Ultra-compact machining center with Higher rigidity than standard BT-30.



BBT30



Cutting Capacity (DM3)

Drill Max. cutting dia **φ20**

Material	Cutting speed	Feed speed	Discharge volume of cutting chips
S50C	2000 rpm	0.30 mm/rev	120 cm ³ /min

Tapping Max. cutting dia **M20 x P2.5**

Material	Cutting speed	Feed speed
S50C	160 rpm	2.5 mm/rev

Endmill Max. cutting capacity **210 cm³/min**

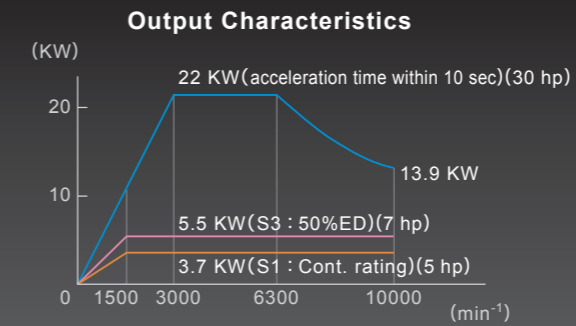
Material	Tool Diameter	Cutting speed	Feed speed	Cutting stock
S50C	φ20	3000 rpm	0.05 mm/tooth	10 mm

Face milling Max. cutting capacity **96 cm³/min**

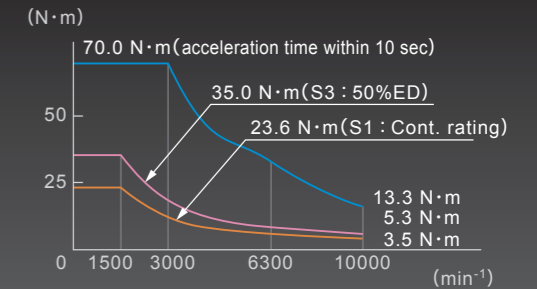
Material	Tool Diameter	Cutting speed	Feed speed	Cutting stock
S50C	φ50	1500 rpm	0.11 mm/tooth	3 mm

Spindle Output Characteristics

3.7 / 5.5 / 22kw



Torque Characteristics



Tools Traveling Range

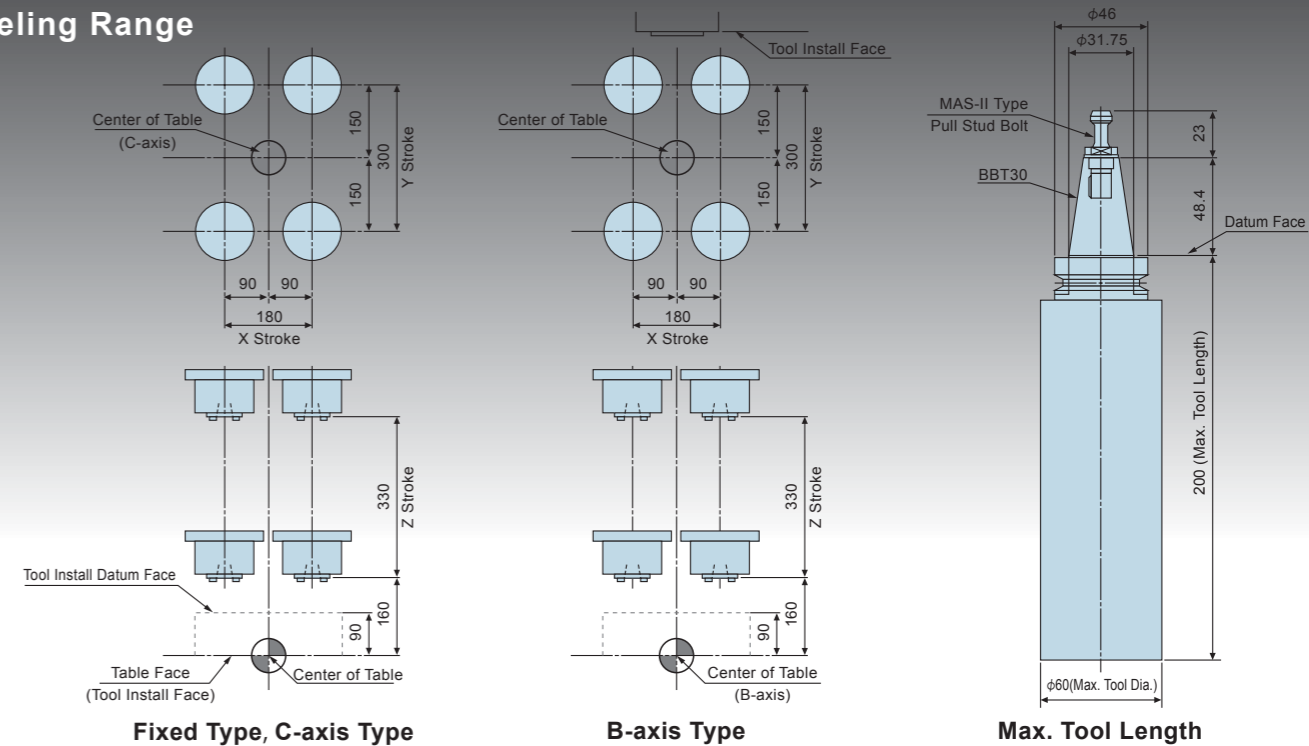


Table Specifications



Item		DM3B	DM3C
		B-axis type	C-axis type
Table Diameter	mm[inch]	φ270[10.63]	φ250[9.84]
Live Tool Speed	min ⁻¹	50	50
Index Time(90°)	sec	0.4	0.5

Module Specifications

Item	DM3
Spindle Speed	min ⁻¹ Max.10000
Spindle Nose	BBT30
Spindle Diameter	mm [inch] φ55 [2.17]
Spindle Motor	KW [hp] 3.7/5.5/22 [5/7/30] (Cont./50%ED/acceleration time within 10 sec)
Construction	X, Y, Z-axis roller guide
Stroke	mm [inch] X-axis : 180 [7.09] Y-axis : 300 [11.81] Z-axis : 330[13.0]
Rapid Traverse	m/min X-axis : 25 Y-axis : 36 Z-axis : 45
Tool Storage	tools 16
Tool Length	mm [inch] Max. 200 [7.87]
Tool Diameter	mm [inch] Max. φ60 [2.4]
Tool Weight	kg / tools Max. 3 [Max. 32 / 16]
ATC (Tool to Tool)	sec 1.8
Module Weight	kg [lb.] 2,500 [5,500]

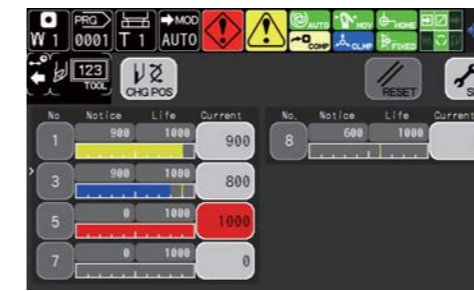
Option

- Rotary joint
- B-axis:Max.8ports (For oil or air)
- C-axis:Max.7ports (For oil or air 7ports,air 1port)
- Air Confirmation
- Part Probe for Spindle (Wireless)
- Through Spindle Coolant



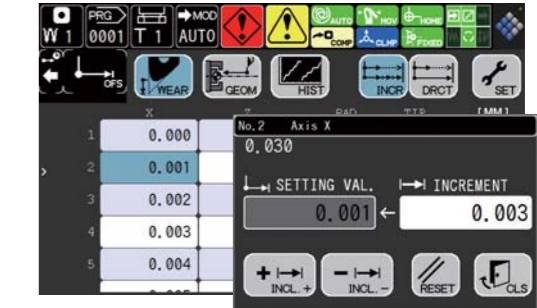
Fuji's own Unicorn controller easily operates both robot and NC functions.

Tool Counter



Only utilized tools will be displayed.
 Monitor tool life and reset counters on a common screen.
 Monitor tool life status via displayed bar graphs.
 Verify tool change procedure on the same screen.
 Prediction before reaching tool life can be set.

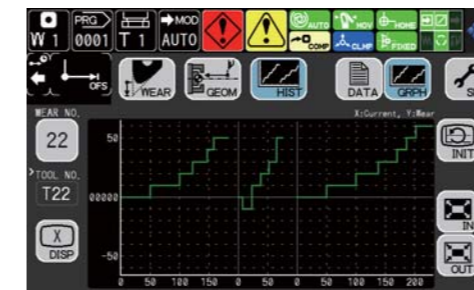
Offset Screen



Known Offset values can be preset.
 Adding offset is possible with easy operation.

Quality Control Support

Offset History



Offset history is displayed in graph form.
 Tool wear status is displayed along with history on the same screen.
 Up to 10 wear correction numbers can be registered.
 The history of up to 200 offsets can be displayed.

Quality Check Counter



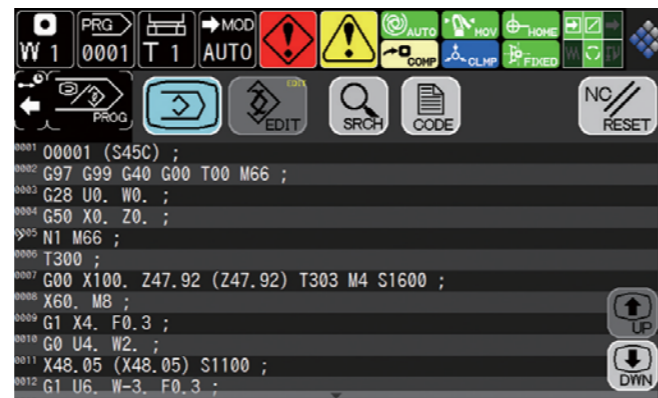
Set up to 8 types of counters.
 Maximum number of digits per counter is 8.
 The count-up timing is set using ladder circuits.

Global Design



Globally accepted, intuitive touch screen panel incorporates an Icon based operational system.

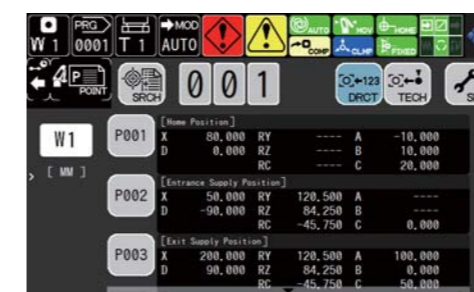
Program



NC and robot controller are common.

Maintenance Function

Robot Point



Directly enter robot motion points or teach the robot's coordinates.
 Create/edit a robot program per NC Program by work select number.

Alarm Message

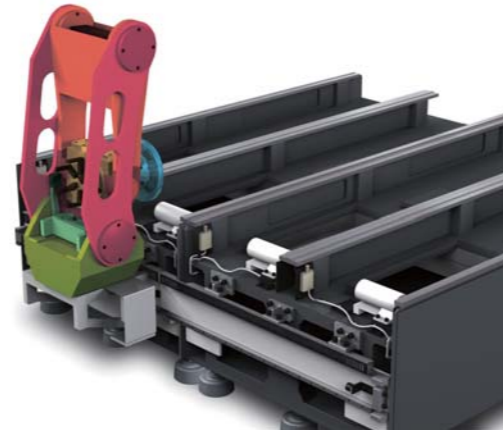
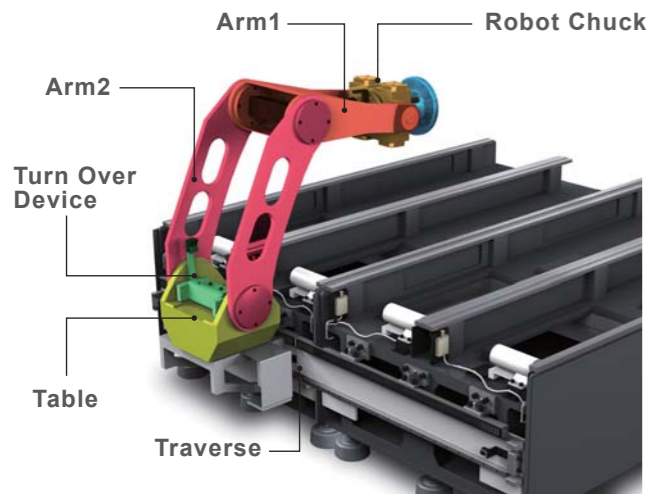


During fault occurrence, the Alarm screen automatically appears.
 On the Alarm screen, you can check detailed descriptions of how to find and correct the fault.
 After the fault is cleared, you can return to the previous screen with a single touch.
 Up to 500 items are recorded in the alarm history.

Transfer Device

DLL3 Multiple Axes Robot

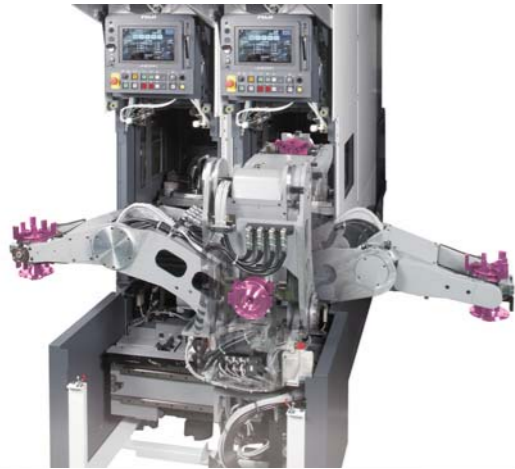
Multiple Axes Robot DLL3



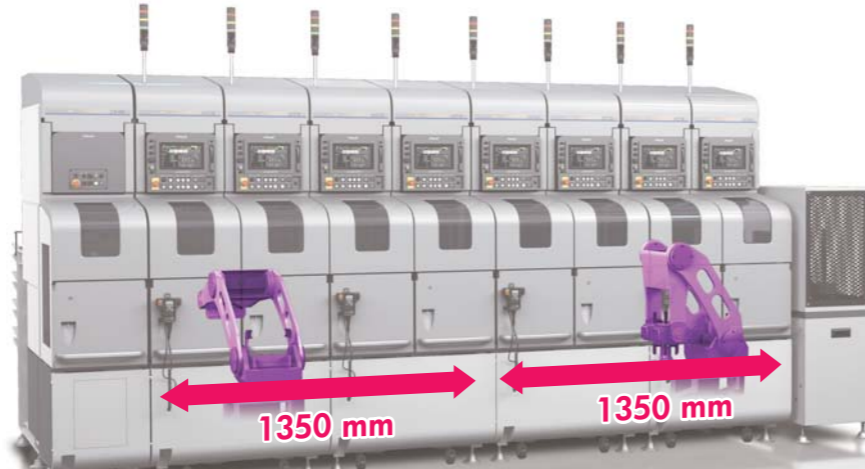
Robot Construction

Part transfer between modules can be conducted while saving space.
 Load / Unload robot chuck.
 Workpiece load /unload 5.8 seconds.
 Workpiece flip station is built into the robot's main body, saving valuable space.

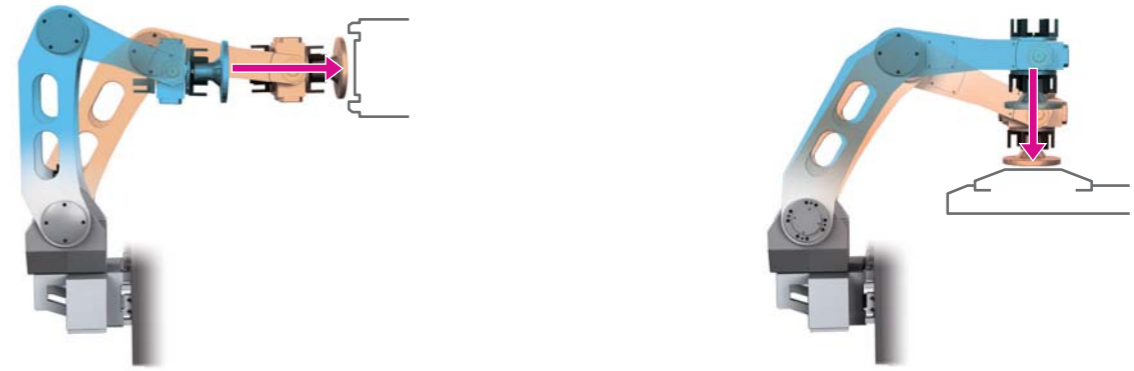
Arm at Home Position



One robot supports two bases.

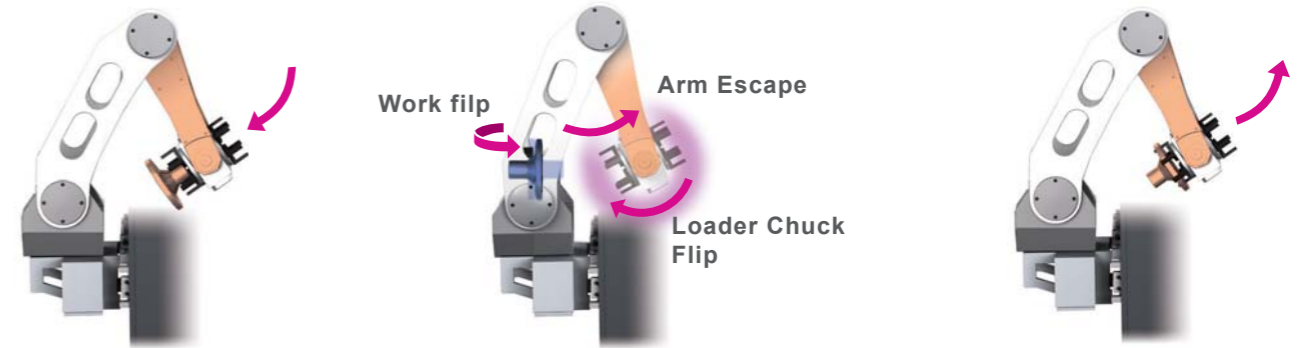


Linear Motion



Simultaneous multi-axes robot movement.

Turn Over Device



Pass the workpiece into turn-over unit

180 degree rotation for turn-over unit

Remove the workpiece from turn-over unit

Robot Specifications

Item		DLL3
Loader Chuck	°/sec	600
Arm1 Rotation Speed	°/sec	270
Arm2 Rotation Speed	°/sec	180
Table Rotation Speed	°/sec	180
Max. Traverse Speed	m / min	Max.100
Max. Front/Back Speed	m / min	Max.70
Max. Up/Down Speed	m / min	Max.70
Carrying Capacity	mm[inch]	φ200 [7.87] × 100 [3.94]
Carrying Capacity	kg [lb.]	5 + 5 [11 + 11]
Min.Tact Time	sec	36
Min. Loading Time	sec	9.6

Peripheral Device



Option

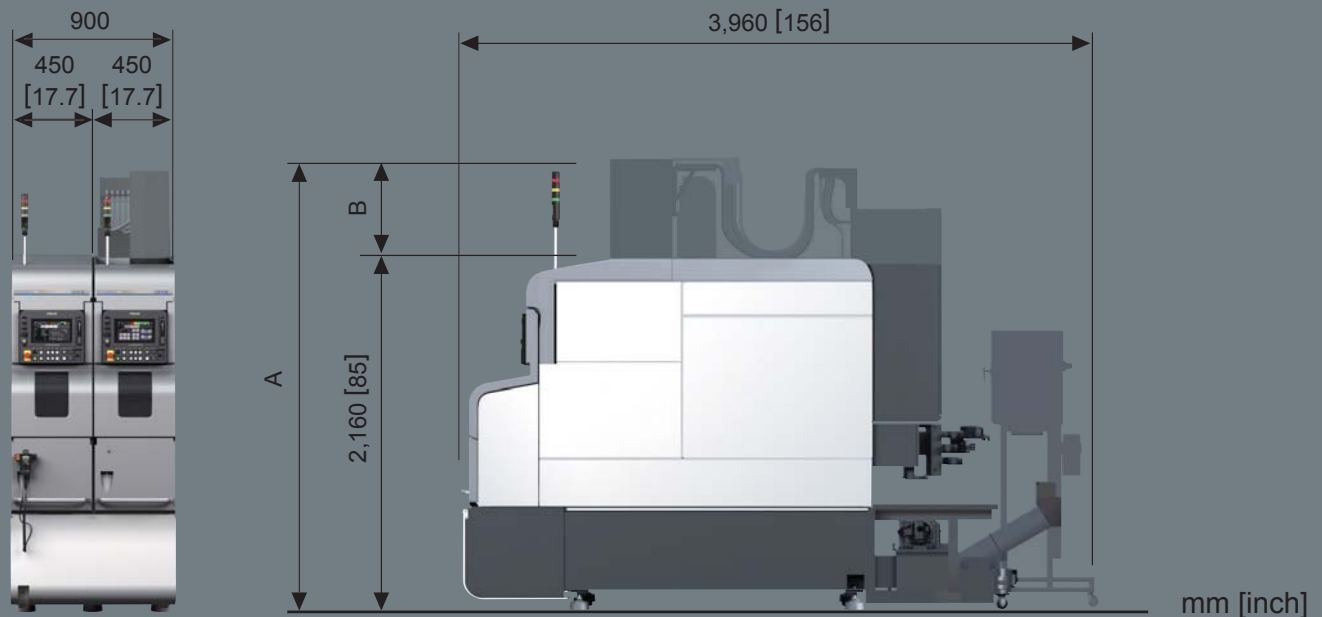
DMC
Conveyor

DMK
Work Table Between Module
Quality Check Table

Chuck



FUJI offers its own designed/fabricated chucks as standard. Fuji, with vast work holding experience will also design and build special chucks specific to your application.



		Lathe Module	Vertical Machining Center Module
A	mm [inch]	2,160 [85]	2,790 [110]
B	mm [inch]	0	630 [24.8]
Module Weight	Kg [lb.]	2,000 [4,400]	2,500 [5,500]

Base Module	Module		450 [17.72] x 2 Modules or 900 [35.43] x 1 Module
	Pull-Out Distance	mm [inch]	700 [27.56] Front
	Chip Conveyor		Screw Type
	Base Weight	kg [lb.]	1,000 [2,200]
Transfer Device	Robot Type		Multiple Axis Robot DLL3
	Carrying Capacity	kg [lb.]	5 [11] + 5 [11]
	Construction		4 Axis Swing Arm + 1 Traverse Axis
	Turn Over Device		OD Clamp + Rotation (Built-in robot)